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M.A.ALIYEV^{1,2}, A.S. ZHAYLAUBAYEVA², DB MUSTAFINOV¹, V.S.KARAVAYEV¹, B.M.AGLAKOV², G.Y. SULEIMENOV¹

¹ Kazakh Medical University of Continuing Education, Almaty

INTRAOPERATIVE NEUROMONITORING IN SPINAL NEUROSURGERY AT ALMATY CITY CLINICAL HOSPITAL № 7

SUMMARY

Intraoperative neuromonitoring represents an opportunity to observe the state of the the nervous system structures during surgical intervention and to define, reduce and prevent neurological deficits prior to the surgery. Intraoperative neuromonitoring remains important, as the surgeon has no neuronavigation information during the operation to remove tumors/ Moreover, constantly changing structures can reduce the quality of the manipulations performed. Therefore, the neurophysiologist who also participates during the operations on the spinal cord "co-work" with the neurosurgeon closely in order to establish the physiological limits of resection, to prevent mechanical damage to the spinal cord and its ganglia: overstretch, rupture, trauma, detection of damage to the vessels in proper time and thereby preventing potential iatrogenic lesions.

41 operations were performed using Nim Eclipse intraoperative neuromonitoring by Medtronic at the Almaty City Clinical Hospital No. 7, This article describes neuromonitoring methods and good results confirming an obtained effectiveness. A total intravenous anesthesia without myorelaxants was performed according to the international standards of anesthesiologists. A close interaction of neurophysiologists, neurosurgeons, anesthesiologists is required in order to improve postoperative results and reduce the risks of neurologic lesions:

Key words: intraoperative neuromonitoring, somatosensory evoked potentials, motor evoked potentials, trigger electromyography, spinal neurosurgery.

Reducing the frequency of intraoperative complications is one of the topical issues of modern neurosurgery. Modern neurosurgical technical equipment helps to prevent and detect abnormalities of the nervous system during the operation, to predict potential complications. Intraoperative neuromonitoring (hereinafter referred to as "IONM") allows real-time evaluation of the integrity of structures at different levels of the National Assembly. This is the gold standard for operations in various areas of the spine: with degenerative diseases, with deformities, removal of spinal cord tumors or trauma complication.

In this article, we performed an analysis of modern representations and possibilities of IONM use according to the literature as well as we took our own data taken during spinal surgical interventions at the City Clinical Hospital No. 7 in Almaty.

The purpose of the study: to study results obtained from applying intraoperative neuromonitoring in the last three years during the spinal cord operations at the City Clinical Hospital No. 7 in Almaty.

Material and methods: since October 2014, the use of IONM on the Nim Eclipse device of Medtronic (USA) was introduced at the City Clinical Hospital No. 7. This allowed recording of all necessary neurophysiological parameters for various types of operations.

The choice of exact IONM modalities was made by a neurophysiologist, according to the protocol of preoperative access planning as well as with consideration of the scope of surgical intervention done by the neurosurgeon. Given the sensitivity of the conduct of the IONM, the anesthetic aid did not use long-acting muscle relaxants, the main stage of anesthesia was maintained on a combination of propofol with fentanyl. According to the international standards of The LAFS (Los Angeles Anesthesia Friendliness Scale) for anesthesiology, patients undergoing IONM undergo total intravenous anesthesia without the use of muscle relaxants.

According to the analysis of the results, 41 surgical interventions with the use of IONM were performed. In particular, installation of stabilizing structures in degenerative-dystrophic changes of the spinal column was as follows - 13; removal of extra- and intramedullary neoplasms – 28 in total. The age of patients varied from 18 to 77 years. Each patient before the operation performed neurophysiological monitoring, analysis of the patient's neurological status, MRI data, and then on intraoperative monitoring regimes with an individual approach in each case. The choice of the modality of IONM in operations on the spinal cord was caused by potentials and myography. Continuous monitoring of the conductivity of the spinal cord, spinal roots and peripheral nerves was performed.

A peripheral receptors response from SSEP (somatosensory evoked potentials) stimulated by electrical impulse was obtained by excitation of the brain sensory cortex (Figure 1). Reducing the amplitude and increasing the latency of the SSVP by 50% was an alarm signal for damage to the structures of the spinal cord. In our case, there was no significant reduction in the indices. Rhythmic

² City Clinical Hospital No.7, Almaty, Kazakhstan

^{*} a.marat.a0903@mail.ru, ORCID 0000-0002-3190-2395



stimulation of the SSEP was carried out from each point alternately to the main stage of the operation to determine

the initial values and then continuously until the necessary manipulations were completed.



Figure 1. Somatosensory evoked potentials with excitation of the sensory cortex of the brain

MEP (motor evoked potentials) in the patients was performed to assess the state of the motor conducting pathways of the spinal cord with the stimulation of the motor cortex by an electrical impulse. To register TkMVP, spinal scalp electrodes were administered subcutaneously at points C3, C4 according to the extended international system "10-20%". The registering needle electrodes were established depending on the level of spinal cord lesion on the target muscles of the upper (m. Deltoideus, M. biceps / triceps brachii, m.tenor, m. abductor hallucis and m. abductor pollicis brevis.) and lower limb (m quadriceps / biceps femoris, m gastrocnemius, m. tibialis anterior), with lumbosacral lesions also on the anal sphincter. Earthing electrodes were injected into intact muscles. After the introduction of electrodes prior to the beginning of the study, in all cases the impedance was checked to verify the correctness of their installation. Reducing the amplitude by 50% and increasing the latency by 10% are the main indicators of the violation in the entire motor chain. Also, it should be noted that factors that significantly affect SSEP: inhalation anesthetics, temperature, blood pressure were also monitored.

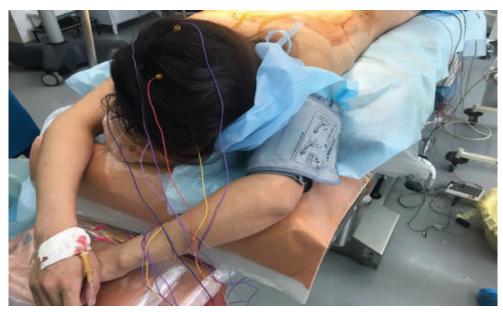
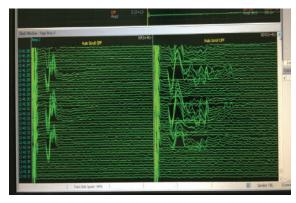


Figure 2. Visible appearance of motor evoked potentials.



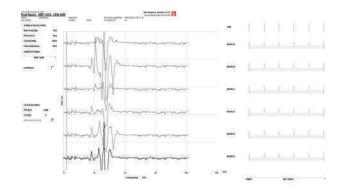


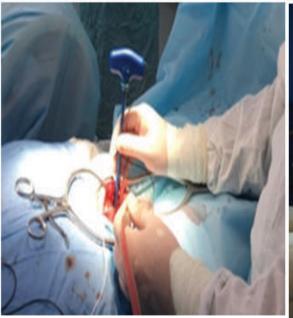
Figure 3. Stages of a persistent fixation.

Direct stimulation by electric impulse or direct mechanical action.

The advantage of the motor response in peripheral stimulation is that it comes with less latency (faster) than with the registration of profit centers. Registration is performed between two needle electrodes mounted on the target muscles, depending on the level of damage. A neurosurgeon using a bipolar or a monopolar probe can accurately determine the roots of the spinal cord and assess the correct location of the screw in the body of the vertebra according to international visualization standards developed by neurophysiologists (Figure 3). If the implanted screw was completely positioned in the bone, it was further

shielded and the electrical stimulation of the screw does not activate the nerve. But if the medial wall of the vertebral body was damaged, a conductor with low resistance between the screw and surrounding tissues is formed. And when the current was applied to the screw, the nerve root was stimulated, the corresponding muscles contracted, and the MVP was recorded.

In this case, a stimulating bipolar and (or) monopolar electrode was used, the current strength was from 7 to 15 mA (Figure 4). Trigger EMG was also used to assess the correct position of transpedicular screws when installing stabilizing structures. In this case, the stimulus strength was 3-5 mA, the duration was 200 ms.



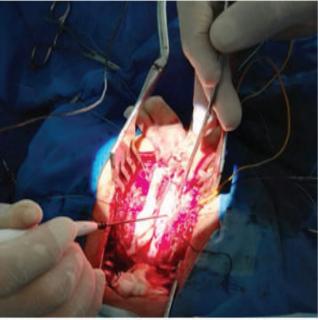


Figure 4. Using a monopolar electrode.

The parameters of registration and stimulation of intraoperative neurophysiological neuromonitoring were performed according to international standards, reflected in Table 1.

^{*} a.marat.a0903@mail.ru, ORCID 0000-0002-3190-2395



 Table 1. Registration and stimulation parameters.

Parameter	AEP	EMG/CMAP	TES MEP	TES MEP	DC MEP	DC MEP	SEP	SEP	EEG	VEP
			transcranial	D-Wave	motoric	Speech	N.medianus	N.tibialis		
Filter										
Hardware High-pass filter (fu)	160	30	30	30	30	30	30	30	0.5	0.5
Software High-pass filter (fu) [0.5	0.5	0.5	0.5	0.5	0.5	0.5/30****	0.5/30*****	0.5	0.5
Software Low-pass filter (fo) [h	3500	2000	2000	3500	2000	2000	600	600	70	100
Gain (mVpp)	1	100	100	100	100	100	10	10	10	10
Number of Averages	1000	-	1	15	-	-	100 (50 300)	150 (50 300)	-	100
Stimulation										
Duration	cont.	cont.	foot switch / cont.	cont.	max. 4 sec.	max. 3 sec	cont.*	cont.*	-	cont.
Stimulation frequency [Hz]	<u>14.3</u> , 18.2	3, 30	0.5-2, ISI 4 ms	1 - 2	0.5-2 ISI 4 ms	50	4.7	3.7	-	1.1
Pulse form	click, suction	rectangle	train, 4-6 pulses	biphasic	train, 4 pulses	pulse, biph.	rectangle pos.	rectangle pos.	-	LED flash
Intensity	90, 95**dB	0,05 <u>0.5</u> 5 mA	<u>40</u> 220 mA	40220 mA supramax.	4 30 mA	<u>4</u> 20 mA	3 30 mA***	3 45 mA***		15 mA
Pulse width [µs]	-	200	500	1000	500	500	200 - 500	200 - 500	-	750/1500****
Max. Voltage [V]		100	300	300	80	80	160	160		120
Display/Analyse										
Time scale [ms]	20	200 per div	130	20	130	-	60	100	-	500
Amplitude scale [µV] (Bio/Aver./	20/0,5/1	500	300	30	300		20/3/5	20/3/5	100	20/3/5
Sweep duration [ms]	20	-	130	30	130		80	130	-	500
Latencies (Peaks)	III, V, III-V	-		3 -15 ms	-	-	N20, P25	P40	-	P100



Figure 5. Removal of intramedullary tumor.







Results of the study and their discussion:

During intraoperative neuromonitoring, minor changes in bioelectrical indices were noted, all stages of operative intervention were performed according to preoperative planning. During the operation, correction of the surgeon's manipulation was performed with:

- 1) a stable decrease in the amplitude of evoked potentials below the baseline by 50%, an increase in latency of 10% (compulsory comparison of data with anesthesia, hypothermia, arterial pressure);
- 2) a stable M-response with stimulation of a transpedicular screw with a current strength of 3-4 mA (oscillations of SSVP and TcMVP up to 30% were considered acceptable). In the case of irritation of motor fibers, M-responses to EMG were obtained, disappearing after the termination of the manipulation. In 5 patients with degenerative-dystrophic changes of the spine, the amplitude of the SSVP was below 0.9 mV during the entire intraoperative period (while maintaining normal latency). Motor disorders of the conductor type developed in one case after surgery for the removal of intramedullary tumors with complete regression during 10-15 days of conservative therapy.

According to the literature, there are reports of false positive and false negative results of neuromonitoring, on average. These data represented approximately 4%, the

most frequent causes of which are anesthesia, temperature in the operating room and blood pressure indicators. [14].

IONM is an additional effective method of intraoperative diagnostics, which allows to reduce the risks of post-operative complications and improve the results of surgical manipulations.

Conclusions: Intraoperative neuromonitoring:

- 1. allows to monitor the functional consistency of motor portions of the conducting pathways of the spinal cord, peripheral structures, and helps to reduce the degree of motor and sensory disorders during the operation.
- 2. helps to find the safest access when removing intramedullary spinal cord tumors and reduces the risk of postoperative neurologic disorders;
- 3. Ensures control and prevention of intraoperative complications with predicting the course of the postoperative period:
- 4. Identifies the anatomical structures within the operating field and contributes to an increase in the radical nature of the operative intervention and the safety of the submerged metal-fixed spinal column without the formation of iatrogenic neurological deficits;
- 5. It is needed for the legal security of the operating surgeon due to the formation of the neurophysiological protocol and its application to the medical documentation.

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^{*} a.marat.a0903@mail.ru, ORCID 0000-0002-3190-2395