

Development of a Gear Hobbing Fixture to Reduce Ineffective Work and Increase the Productivity using Ergonomics

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Abstract--The present work deals with the development of a gear hobbing fixture for manufacturing of gear drive of fuel pump hobbled on Lambert 82 machine. The primary objective is to reduce the time & improve the current working method of manual clamping by using screw clamp. This is achieved by replacing the existing method with a hydraulically actuated clamping and de-clamping mechanism activated by a switch, thus using ergonomic principle of reducing the manual efforts required. In addition to this the other important criteria to be considered are cutting forces and shear experienced, along with total runout, positive location, repeatability, production rate and reliability .

Keywords – fixture, productivity, ineffective work, clamping mechanism, disc springs, hydraulic and pneumatics, switch, ergonomics, BRIEF survey

INTRODUCTION

Gear Hobbing is a widely applied manufacturing process for the construction of any external tooth form developed uniformly about a rotating centre. It is an advance process compared to turning and milling [6]. The fixture used for hobbing process should be designed such that the gear blank is clamped accurately about the machining axis and restrain any undesirable movement throughout the machining. Fixtures consisting of clamps and locators should also ensure a good quality performance beside positioning and holding. Michael Yu Wang [7] stated that fixture layout is the fundamental task of fixture design, to determine the number, type and location of the basic fixturing elements of locators, supports, and clamps, as opposed to the detailed design of the fixture assembly. Ineffective work can be defined as any efforts put into any process which does not contribute to the productivity, profit or significant returns, and results in wastage of time and energy. Human factors and ergonomics (HF&E), also known as comfort design, functional design, and systems, is the practice of designing products, systems, or processes to take proper account of the interaction between them and the people who use them. In this project we are dealing with the physical ergonomics, which is concerned with human anatomy, and some of the anthropometric, physiological and bio mechanical characteristics as they relate to physical activity.

PROBLEM FORMULATION

Fixtures are very vital parts of conventional as well as modern manufacturing processes since it directly affects the productivity and quality. The total machining time for a workpiece includes work-handling, the methods of locating and clamping and the total machining time should be as minimum as possible. The fixture should also ease the loading and unloading of the workpiece, which will help to reduce the ideal time.



Fig.1 Screw clamping

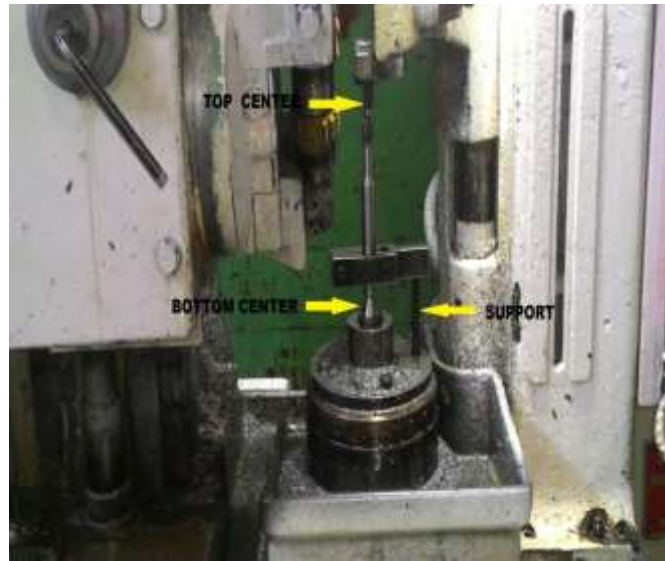


Fig.2 Workpiece with support

The time taken for setting of the workpiece on the machine was quite high. The above figure explains that the operator first need to hold the workpiece in the clamp and tighten the screw, then hold the workpiece between the centres and wait until the top centre of the machine touches the workpiece. Then as the base table starts rotating, the support shown in the figure which connects the extended portion of the clamp and the base, rotates the workpiece along with the base table. As you can see, this technique of setting the workpiece is not reliable and tedious for the operator when a batch of about 150-200 such gears is to be machined. The chances of job rejection are also very high due to the following reasons-

(A conditional runout tolerance of only **25 microns** is permitted)

- The centres cannot hold the workpiece very firmly due to the high cutting forces.
- Due to the tedious repetitive cycle of setting the workpiece the operator might not properly set the extended part of the clamp on the support.

CONDITIONS TO BE CONSIDERED WHILE DESIGNING THE FIXTURE

- Ergonomics

The existing process is very tedious for the operator and he is subjected to fatigue along with various risk factors and thus a simpler clamping system is to be designed.

- Runout tolerance

As the job is used to drive the fuel pump, runout of the job to be maintained is restricted to only **25 microns**. Therefore the fixture should clamp the workpiece uniformly and within the runout limit

- Power operated clamping and de-clamping mechanism

As the primary aim is to reduce the ineffective work introduced due to the manual clamping of the workpiece, we have to use power operated mechanism. Various options were considered like using electric motor, vacuum pump and hydraulic-pneumatic power to actuate the clamps.

Due to lack of space, high operating cost and difficulties in effectively implementing the mechanism, the options like electric motor and vacuum pump were obviated. The most viable solution was to use Hydraulic and Pneumatic power. The implementation of the mechanism using the hydraulic-pneumatic source is explained later in the coming section.

- Tool travel

The upper and lower limit of tool travel from the base is 8.1” and 2.95” respectively. Therefore we have to maintain the portion of the job to be machined within these limits.

DEVELOPMENT OF MECHANISM AND ITS IMPLEMENTATION

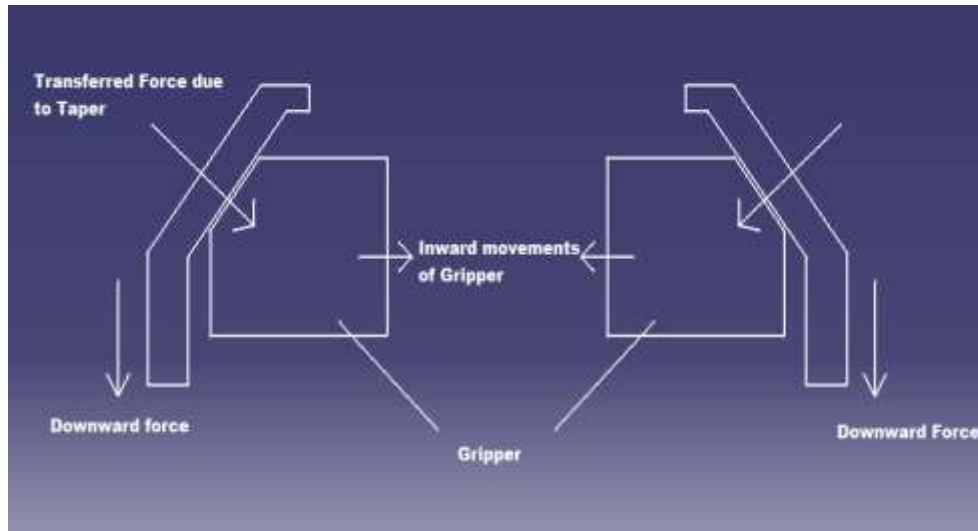


Fig.3 Block Diagram of Basic Mechanism

A simple clamping mechanism is used as shown in figure consisting of grippers and a taper part having linear vertical motion. The taper portion of the outer part is in contact with the taper edge of the gripper. As the outer part moves downwards, the gripper starts moving inwards. This simple principle is used to develop the clamping mechanism of the fixture.

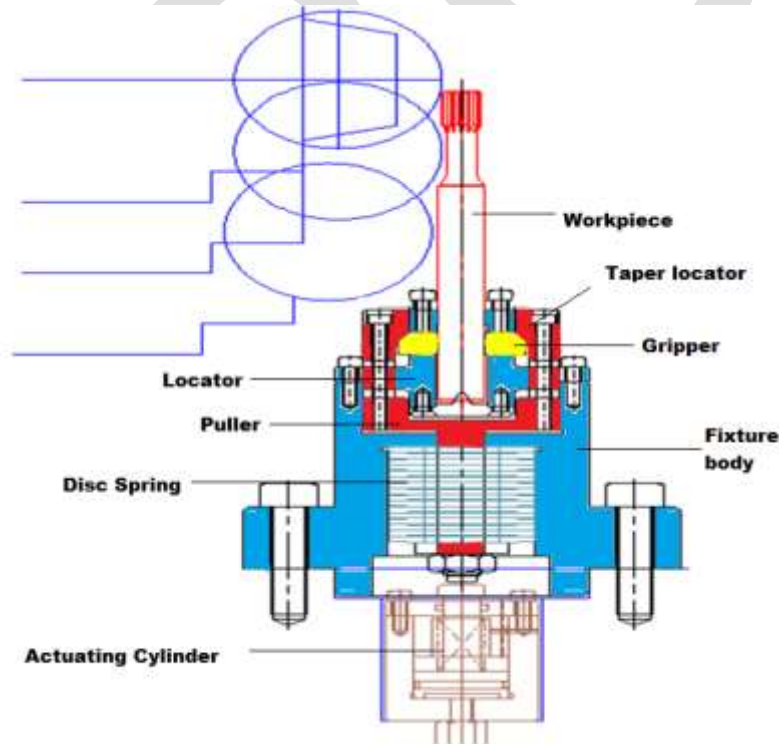


Fig.4 Sectional View of the fixture

Challenges

The challenge while implementing the above described mechanism was that there are two motions to be considered

- Linear Motion of taper locator, puller and gripper during clamping (shown in Red colour)
- Rotation of the total fixture, as it has to be attached to the base plate. (achieved with the help of blue coloured parts)

The Taper Locator and Puller are used to clamp the workpiece in position and have linear vertical motion. The puller by default is pulled downward due to the spring action of disc spring. Due to this downward motion of taper locator, the grippers move inwards and thus clamp the workpiece.

To de-clamp the workpiece an actuating cylinder, attached below the base table, which has a very small clearance between the piston and the puller end, is used. This cylinder is hydraulically powered and pushes the puller upwards which moves the taper locator upwards and thus generates a clearance between the gripper and taper locator. Thus the grippers become free slides in guides provided and they can move outwards and job can be removed.

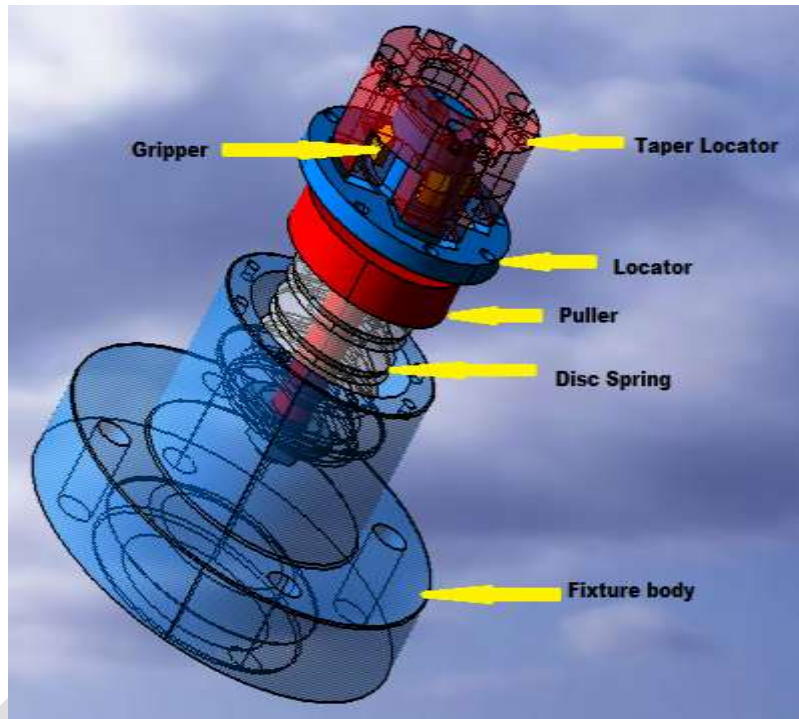


Fig.5 3-D Exploded view of the Fixture

In order to make the fixture rotate with the base table, the Taper Locator is interlocked with the Locator. From the figure, we can see that the taper locator has projected ends which fit into the slots in the locator. The locator is attached to the fixture body which is attached to the base. This arrangement rotates the fixture (hence the workpiece) with the same RPM as that of the table.

DISC SPRINGS

As mentioned in the above condition of Tool Travel, the combined height of the fixture and workpiece should not cross the upper limit of the tool travel. By using conventional helical spring there is a possibility of exceeding this limit, therefore we will be using Disc Spring which exerts the same force as that of a helical spring but with lesser space requirement and deflection.

Advantages of Disc Spring are-

- High load capacity with small deflection
- High load to size ratio
- Consistent performance under design loads
- Longer fatigue life
- Flexibility in stack arrangement to meet the desired load requirement

HYDRAULIC & PNEUMATIC CIRCUIT

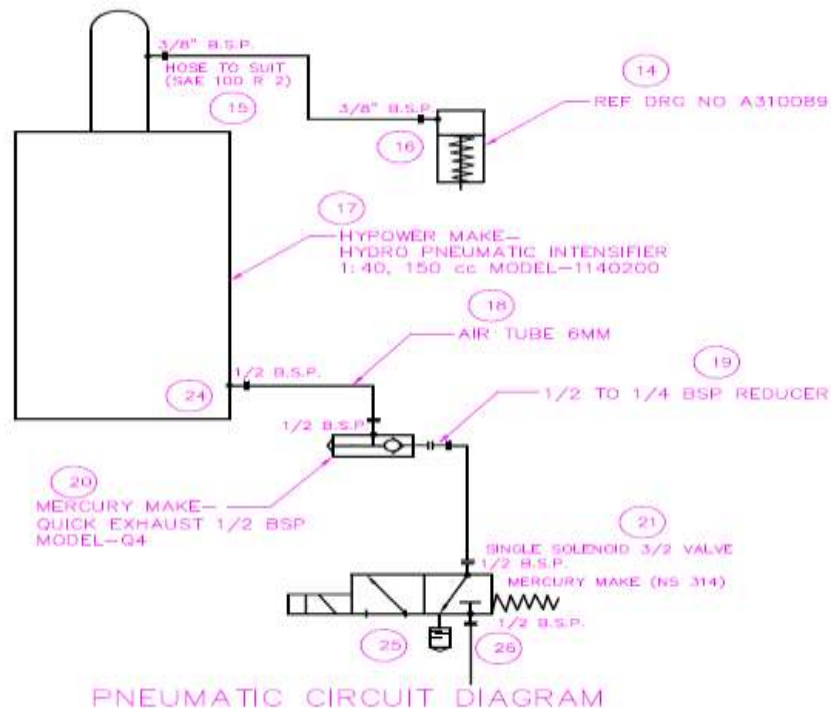


Fig.6 Pneumatic circuit Diagram

The available power supply in the company was Pneumatic supply of 3.5bar which is used for the cleaning of the burr by compressed air gun, this same supply is to be used to actuate the cylinder which in turns de-clamps the job. This pressure isn't enough to de-clamp and also this line is common to all the machines in the plant, there is a possibility of pressure drop as there might be another operator using it. Hence to compensate for this loss and to avoid any interruption in the operation of the fixture mechanism we have used an intensifier in the circuit of ratio 1:40. The line after the intensifier is hydraulic using oil of grade SAE100R2.

RESULTS AND DISCUSSIONS

1. TIME-SAVING

The time measured for setting and handling of the job without fixture was about 11sec and with fixture it is 5sec.

2. ERGONOMICS

BRIEF Survey (Baseline Risk Identification of Ergonomics Factors).The BRIEF Survey is intended to find any ergonomic risk factors that may cause any musculoskeletal symptoms to the employee operating the machine. Lower the score of the survey, greater will be the safety and better ergonomics. The BRIEF Survey of the process shows a very significant improvement from 30 to 8 points.

Before improvement

BRIEF™ Survey - Sources for Identification of Ergonomic Factors

Step 1. Complete Job Information
 Gear
 Gear

Step 2. Circle Posture and Force posture when job factors are observed. Mark Posture and Force boxes by each Body Part when Posture or Force is observed.

Body Part	Posture	Force	Posture	Force	Posture	Force	Posture	Force
Neck								
Shoulder								
Elbow								
Wrist								
Hand								
Lower Back								
Upper Back								
Leg								
Foot								

Step 3. For each job with Posture or Force posture, mark each observation frequency (number) when posture or force is observed.

Step 4. Add Posture, Force, Duration and Frequency values under the respective Job Rating (0-5) column (0, 1, 2, 3, 4, 5).

Step 5. Identify Potential Problems

Fig.7
(Before Improvement)

BEST™ - BEST™ - Common Sense Testing

Step 1. Complete Job Information

Step 2. Circle BEST Score

Job Rating	Posture	Force	Posture	Force	Posture	Force	Posture	Force
3	2	2	0	0	2	2	0	0

Step 3. Determine Common Factors

Common Factor	Posture	Force	Posture	Force	Posture	Force	Posture	Force
1	5	3	3	3	0	0	3	3

Step 4. Determine Potential Problems

Potential Problem	Posture	Force	Posture	Force	Posture	Force	Posture	Force
1	0	0	2	0	2			

Step 5. Calculate Job Risk Factor Score

Step 6. Determine the Exposure Multiplier

Step 7. Calculate Job Hazard Score

30

EXPECTS NO MORE AFTER IMPROVEMENT

Fig.8
(Before Improvement)

After improvement - expected

BRIEF™ Survey - Sources for Identification of Ergonomic Factors

Step 1. Complete Job Information
 Gear
 Gear

Step 2. Circle Posture and Force posture when job factors are observed. Mark Posture and Force boxes by each Body Part when Posture or Force is observed.

Body Part	Posture	Force	Posture	Force	Posture	Force	Posture	Force
Neck								
Shoulder								
Elbow								
Wrist								
Hand								
Lower Back								
Upper Back								
Leg								
Foot								

Step 3. For each job with Posture or Force posture, mark each observation frequency (number) when posture or force is observed.

Step 4. Add Posture, Force, Duration and Frequency values under the respective Job Rating (0-5) column (0, 1, 2, 3, 4, 5).

Step 5. Identify Potential Problems

Fig.9
(After Improvement)

BEST™ - BEST™ - Common Sense Testing

Step 1. Complete Job Information

Step 2. Circle BEST Score

Job Rating	Posture	Force	Posture	Force	Posture	Force	Posture	Force
0	0	0	0	0	2	2	0	0

Step 3. Determine Common Factors

Common Factor	Posture	Force	Posture	Force	Posture	Force	Posture	Force
1	0	0	0	0	0	0	0	0

Step 4. Determine Potential Problems

Potential Problem	Posture	Force	Posture	Force	Posture	Force	Posture	Force
1	0	0	0	0	0	0	0	0

Step 5. Calculate Job Risk Factor Score

Step 6. Determine the Exposure Multiplier

Step 7. Calculate Job Hazard Score

0

EXPECTS NO MORE AFTER IMPROVEMENT

Fig.10
(After Improvement)

3. PRODUCTIVITY

Number of jobs rejected per 100 jobs manufactured without fixture = 2
 Number of jobs rejected per 100 jobs manufactured with fixture = 0
 Therefore, Material Productivity without fixture = 98%
 Material productivity with fixture = 100%

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CONCLUSION

With the ever increasing demand and pace of production it is necessary to improve the process of production. The proposed clamping mechanism has successfully reduced the ineffective work and the risk factors and eventually results in an over-all increase in the productivity. The mechanism introduced here can be used to develop similar fixtures which demand clamping of any circular workpiece.

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