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## INTEGRATION BY PARTS FORMULAS AND FORMULATION OF FEYNMAN PATH INTEGRAL


#### Abstract

This paper aimed at investigating the Integration by Parts Formulas and Rotationally Invariant Sobolev Calculus on Free Loop Spaces of a manifold mechanics. This formulation is very familiar to us and well known to be useful. But its rigorous meaning is given little except for special cases.


Key words: Sobolev calculus, loop space, Laplacian, Feynman path integral, Lagrangian function, Schrödinger equation, Continuous uniformly.

## Language: English

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## Introduction

In [2] the project of understanding some of the analytical properties of Chen forms by discussing the $L^{p}$-theory of Chen forms is started. Then $\Delta$ is a uniformly elliptic second order differential operator. let $\Omega_{x}$ be the space of loops in $\mathbb{R}^{d}$ which start at $x$ and return to $x$ after a time period 1 . Let $d p_{1}^{x, x}$ be the Brownian bridge measure on $\Omega_{x}$.

Let $H\left(\mathbb{R}^{d}\right)$ be the Hilbert space of paths $H$ : $[0,1] \rightarrow \mathbb{R}^{d}$ which are absolutely continuous with square integrable derivative, equipped with the norm

$$
\|H\|^{2}=\int_{0}^{1}|H(t)|^{2} d t+\int_{0}^{1}\left|\frac{d H(t)}{d t}\right|^{2} d t
$$

Now, as in [2], for each loop $w \in \Omega$ we consider the Hilbert space $\mathrm{H}_{w}$ consisting of the vector fields along the loop $w$ of the form $\mathrm{X}=\tau H$ with periodicity assumption where $(\tau H)_{\mathrm{t}}=\tau_{\mathrm{t}}(w) H_{t}$ with $\tau_{\mathrm{t}}(w)$ being stochastic parallel transport along the loop $w$. These Hilbert spaces form a measurable field of tangent Hilbert spaces on the loop space and they will play the role of the tangent spaces of the loop space.

These Hilbert spaces form a measurable field of tangent Hilbert spaces on the loop space and they will play the role of the tangent spaces of the loop space.

The basic tool in setting up this Sobolev calculus is integration by parts formulas. In [3] we use the Peano approximation to the diffusion associated to $\Delta$, which leads to suitable finite dimensional approximations to the Bismut measure $\mu$. In [3], we define a Skorohod anticipative integral (see [4]) and an Ornstein-Uhlenbeck operator $L$ such that these functions belong to the domain of $L^{p}$ for each $p>0$.

Let M be a compact Riemannian manifold of dimension d and let $P(M)$ be the space of all continuous maps $w:[0,1] \rightarrow M$. Let $v$ be the measure $\mathrm{P}_{1}(x, y) d \mathrm{P}_{1}^{x, y} d x d y$ on $\mathrm{P}(\mathrm{M})$, where $\mathrm{P}_{1}(x, y)$ is the heat kernel of M and $d \mathrm{P}_{1}^{x, y}$ is the Brownian bridge measure on $\mathrm{P}_{x, y}(\mathrm{M})$, the space of paths joining $x$ to $y$. We use the notation $\mathrm{E}_{\mathrm{P}}$ for expectations computed with respect to this measure.

$$
\text { Let } \quad V(t, x) \in \mathrm{R}, A(t, x)=\left(A_{1}, \ldots, A_{d}\right) \in
$$ $\mathrm{R}^{d}\left(x \in R^{d}, t \in[0, T]\right)$ be the electromagnetic potentials, which are defined from

$$
\begin{gathered}
E_{j}=-\frac{\partial A_{j}}{\partial t}-\frac{\partial V}{\partial x_{j}}(j=1, \ldots, d) \\
d\left(\sum_{j=1}^{d} A_{j} d x_{j}\right)=\sum_{1 \leq j<k \leq d} B_{j k} d x_{j} \wedge d x_{k} \quad \text { on } \mathrm{R}^{d}
\end{gathered}
$$

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for the electric strength $E(t, x)=\left(E_{1}, \ldots E_{d}\right)$ and the magnetic strength tensor $\left(B_{j k}(t, x)\right)_{1 \leq j<k \leq d}$. Then the Lagrangian function, the Hamiltonian, and the Schrödinger equation are given by
$\mathcal{L}=(t, x, \dot{x})=\frac{m}{2}|\dot{x}|^{2}+(\dot{x} \cdot A-V), x \in \mathrm{R}^{d}$,
$H(t)=\frac{1}{2 m} \sum_{j=1}^{d}\left(\hbar D_{x_{j}}-A_{j}\right)^{2}+V\left(D_{x_{j}}=\frac{\partial}{i \partial x_{j}}\right)$,
and

$$
\begin{equation*}
i \hbar \frac{\partial}{\partial t} u(t)=H(t) u(t) \quad(t \in[s, T]), u(s)=f \tag{4.1}
\end{equation*}
$$

respectively. We sometimes write the solution $u(t)$
of (4.1) as $U(t, s) f$. For a multiindex

$$
\begin{aligned}
& \alpha=\left(\alpha_{1}, \ldots, \alpha_{d}\right) \text { we write } \\
& \partial_{x}^{\alpha}=\left(\partial / \partial x_{1}\right)^{\alpha_{1}} \ldots\left(\partial / \partial x_{d}\right)^{\alpha_{d}} \text { and } \\
& |\alpha|=\sum_{j=1}^{d} \alpha_{j}
\end{aligned}
$$

Feynman in [6,7] expressed the solution of (4.1) in the integral form, which is called the Feynman path integral,

$$
\begin{equation*}
U(t, s) f=\frac{1}{\mathrm{~N}} \int_{\Gamma_{x}} e^{i \hbar^{-1 s(\gamma)}} f(\gamma(s)) \mu(d \gamma) \tag{5.1}
\end{equation*}
$$

$$
\begin{equation*}
C(\Delta) f=\prod_{j=1}^{n} \sqrt{\frac{m}{2 \pi i \hbar\left(t_{j}-t_{j-1}\right)}} \int_{\mathrm{R}^{d}} \ldots \int_{\mathrm{R}^{d}} e^{i \hbar^{-1 S\left(\gamma_{\Delta}\right)}} f\left(x^{(0)}\right) d x^{(0)} d x^{(1)} \ldots d x^{(n-1)} . \tag{6.1}
\end{equation*}
$$

## II. Preliminaries

To define a connection $\nabla$ on the tangent spaces to $P(\mathrm{M})$ suppose X and $Y$ are vector fields on $P(\mathrm{M})$, that is, sections of the field of Hilbert spaces $\mathscr{H}$. Now $Y=\tau K$ and we can write out $K$ in components

$$
K(w)=\sum_{i=1}^{d} k^{i}(w) V_{i}\left(w_{0}\right),
$$

where the $\mathrm{K}^{i}$ are functions on $P(\mathrm{M})$ and the $V_{i}$ are vector fields on M . Now define $\nabla_{\mathrm{X}} \mathrm{K}$ by the formula
where $\mu(d \gamma)$ is a uniform measure on $\left(\mathrm{R}^{d}\right)^{[s, t]}$ and $N$ is a normalization factor.

In $[8,9,10,11,12]$, etc., equations with the potentials

$$
\begin{align*}
& V=\sum_{j, k=1}^{d} a_{j k} x_{j} x_{k}+\sum_{j=1}^{d} b_{j} x_{j}+\int_{\mathrm{R}^{d}} e^{i x \cdot y} v(d y),  \tag{2.1}\\
& A_{l}=\sum_{j=1}^{d} c_{l j} x_{j}+d_{l} \quad(l=1, \ldots, d) \tag{3.1}
\end{align*}
$$

were studied, where $a_{j k}, b_{j}, c_{l j}$ and $d_{l}$ are constants and $v(d y)$ is a complex measure of bounded variation on $\mathrm{R}^{d}$.

We study the formulation of the Feynman path integral through broken line paths. This formulation is very familiar to us and well known to be useful. We show rigorously for some class of potentials that this formulation is well defined and that this Feynman path integral gives the probability amplitude, i.e., the solution of the Schrödinger equation.

Let $\Delta$ be the subdivision of $[0, t]$ above and $x^{(j)} \in \mathrm{R}^{d}(\mathrm{j}=0,1, \ldots, \mathrm{n}-1)$. We denote by $\gamma_{\Delta}=$ $\gamma_{\Delta}\left(x^{(0)}, x^{(1)}, \ldots, x^{(n-1)}, x\right) \in\left(\mathrm{R}^{d}\right)^{[0, t]}$ the broken line path joining

$$
\left(t_{j}, x^{(j)}\right)\left(j=0,1, \ldots, n, x^{(n)}=x\right) . \text { Set }
$$

$$
\begin{align*}
\left(\nabla_{\mathrm{X}} \mathrm{~K}\right)_{w}=\sum_{i=1}^{d}\langle & \left.d \mathrm{k}^{i}, \mathrm{X}\right\rangle_{w} V_{i}\left(w_{0}\right) \\
& +k^{i}(w)\left(\nabla_{\mathrm{X}_{0}} V_{i}\right)_{w_{0}} \tag{1.2}
\end{align*}
$$

and define $\nabla_{\mathrm{X}} Y$ by $\nabla_{\mathrm{X}} Y=\tau \nabla_{\mathrm{X}} \mathrm{K}$.
Theorem (1.2): For any smooth function $f$ : $\mathrm{M}^{k} \rightarrow \mathbb{R}$ and any set of times $u=\left(u_{1}, \ldots, u_{k}\right)$ with
$0<u_{1}<\cdots<u_{k}<1$ let F be the function on $P(\mathrm{M})$ given by $F(w)=f\left(w\left(u_{1}\right), \ldots, w\left(u_{k}\right)\right)$. Then we have the following integration by parts formula:

$$
\begin{equation*}
E_{P}[\langle d F, \mathrm{X}\rangle]=E_{P}\left[F\left(\operatorname{div} \mathrm{X}_{0}\left(w_{0}\right)+\int_{0}^{1}\left\langle\tau_{s} h_{s}, \delta w_{s}\right\rangle+\frac{1}{2} \int_{0}^{1}\left\langle S_{\tau_{s} H_{s}}, \delta w_{s}\right\rangle\right)\right], \tag{2.2}
\end{equation*}
$$

where X is a vector field on $P(\mathrm{M}), \mathrm{S}$ is the Ricci tensor of M and $\delta$ the It $\hat{o}$ integral.

Lemma (2.2): Let S and T be two stopping times. There exist semi-martingale processes A and $B$ such that $A_{S}$ and $B_{s}$ are smooth functions of $w_{S}$ with values in forms such that $\sum_{\mathrm{S}<\mathrm{t}_{\mathrm{i}}<T} \operatorname{div} X_{\mathrm{t}_{\mathrm{i}}}^{\mathrm{N}}$ converges as $\mathrm{N} \rightarrow \infty$ to

$$
\int_{S}^{T}\left\langle A_{s}\left(X_{s}\right), \delta w_{s}\right\rangle+\int_{S}^{T} B_{s}\left(X_{s}\right) d s
$$

Proof: We can suppose that over the interval $[S, T]$ the process lies in a local chart for $M$. We work in normal coordinates. If $\tau_{s}^{N}$ is parallel transport along the geodesic joining $w_{t_{i-1}}$ to $w_{t_{i}}$ for $i \geq 1$ it follows that

$$
\begin{equation*}
d \tau_{s}^{N}=-\Gamma_{\tau_{s}^{N}}\left(w_{t_{i-1}}+s\left(w_{t_{i}}-w_{t_{i-1}}\right)\right)\left(w_{t_{i}}-w_{t_{i-1}}\right) d s, \quad \tau_{0}^{N}=\tau_{i-1}^{N}, \tag{3.2}
\end{equation*}
$$

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where the Christoffel matrix $\Gamma$ is zero at $w_{t_{i-1}}$, is the analogue of the cancellation which appears in ref. [3] and we deduce that

$$
\begin{gather*}
\operatorname{div} X_{t_{i}}^{N}=A^{\prime}\left(w_{t_{i-1}}, X_{t_{i-1}}^{N}+\left(t_{i+1}-t_{i}\right) \tau_{i-1}^{N} h_{t_{i-1}}\right)\left(w_{t_{i}}-w_{t_{i-1}}\right)+ \\
B^{\prime}\left(w_{t_{i-1}}, X_{t_{i-1}}^{N}+\left(t_{i+1}-t_{i}\right) \tau_{i-1}^{N} h_{t_{i}-1}\right)\left(w_{t_{i}}-w_{t_{i-1}}\right)^{2}+o\left(\left(w_{t_{i}}-w_{t_{i-1}}\right)^{3}\right)+o\left(t_{i}-t_{i-1}\right), \tag{4.2}
\end{gather*}
$$

and the proof of Lemma (2.2) is completed in the
From both previous lemmas we see that same way as the proof of Lemma(1.1.4)[1].

$$
\begin{equation*}
E_{P}[\langle d F, X\rangle]=E_{P}\left[F\left(\operatorname{div} X_{0}+\int_{0}^{1}\left\langle A\left(X_{s}\right), \delta w_{s}\right\rangle+\int_{0}^{1}\left\langle B\left(\tau_{s} h_{s}\right), \delta w_{s}\right\rangle+\int_{0}^{1} C\left(X_{s}\right) d s+\int_{0}^{1} D\left(\tau_{s} h_{s}\right)\right)\right] . \tag{5.2}
\end{equation*}
$$

If $X_{0}=0$ we know that the sum of the above integrals is equal to

$$
\int_{0}^{1}\left\langle\tau_{s} h_{s}, \delta w_{s}\right\rangle+\frac{1}{2} \int_{0}^{1}\left\langle S_{\tau_{s} H_{s}} \delta w_{s}\right\rangle
$$

The formula for $E_{P}[\langle d F, X\rangle]$ can be extended to all previsible $h_{s}$ bounded in $L^{2}$.

Moreover $A, B, C, D$ have the same shape as in [9]. However, if $\bar{A}, \bar{B}, \bar{C}$, and $\bar{D}$ are processes of this particularly nice type such that for all $X_{s}=\tau_{s} H_{s}$, where $H_{s}=\int_{0}^{s} h_{u} d u$ with $h$ previsible and bounded, we have

$$
\begin{aligned}
\int_{0}^{1}\left\langle\bar{A}\left(X_{s}\right), \delta w_{s}\right\rangle+ & \int_{0}^{1}\left\langle\bar{B}\left(\tau_{s} h_{s}\right), \delta w_{s}\right\rangle+\int_{0}^{1} \bar{C}\left(X_{s}\right) d s \\
& +\int_{0}^{1} \bar{D}\left(\tau_{s} h_{s}\right) d s=0
\end{aligned}
$$

then it follows that $\bar{A}=\bar{B}=\bar{C}=\bar{D}=0$.

If $\bar{B}$ is not zero we can choose a stopping time $T<1$, with probability strictly positive, and a deterministic process $\tilde{h}_{s}$ with $\widetilde{h}^{(k)}(0) \neq 0$ such that on the condition that $F_{T}<1$, if we take $h_{s}=h_{T+s}$, the sum of the four integrals in the above formula has a density such that from Malliavin calculus we deduce from the same type of argument that $\bar{A}=0$. For all $X_{s}$ we have

$$
\int_{0}^{1} \bar{C}\left(X_{s}\right) d s+\int_{0}^{1} \bar{D}\left(\tau_{s} h_{s}\right) d s=0 .
$$

But $\bar{D}$ is a smooth function in $w_{s}$. We deduce that $\bar{D}\left(\tau_{s}\right)$ has bounded variation, and from stochastic calculus it is constant.

That implies $\bar{C}=0$.
Proposition (2.3): Let V and A satisfy the assumptions of the Theorem. Then there exists a continuous function $\mathrm{q}(\mathrm{t}, \mathrm{s} ; \mathrm{x}, \mathrm{w})$ in

## $0 \leq \mathrm{s} \leq \mathrm{t} \leq \mathrm{T}, \mathrm{x}, \omega \in \mathrm{R}^{\mathrm{d}}$ <br> satisfying

 $\left(\left|\partial_{\omega}^{\alpha} \partial_{\mathrm{x}}^{\beta} \mathrm{p}(\mathrm{x}, \mathrm{w})\right| \leq \mathrm{C}_{\alpha \beta}\langle\mathrm{x} ; \mathrm{w}\rangle^{\mathrm{M}}, \quad \mathrm{x}, \omega \in \mathrm{R}^{\mathrm{d}}\right)$ with an M so that for $\mathrm{f} \in \mathrm{S}$$$
\begin{align*}
\left\{i \hbar \frac{\partial}{\partial t}-H(t)\right\} \mathcal{C}(t, s) f & =\sqrt{t-s} \sqrt{\frac{m}{2 \pi i \hbar(t-s)}}^{d} \\
& \times \int e^{i \hbar^{-1} \mathrm{~s}\left(\gamma_{x, y}^{t, s}\right) \mathrm{q}\left(t, s ; x, \frac{x-y}{\sqrt{(t-s)}}\right) f(y) d y, \quad 0 \leq \mathrm{s}<\mathrm{t} \leq \mathrm{T}} \tag{6.2}
\end{align*}
$$

Proof: By direct calculations we have
from(3.1),

$$
\begin{gather*}
\left\{i \hbar \frac{\partial}{\partial t}-H(t)\right\} \mathcal{C}(t, s) f=-\sqrt{\frac{m}{2 \pi i \hbar(t-s)}} \times \int e^{i \hbar^{-1} \mathrm{~S}\left(\gamma_{x, y}^{t, s}\right)}\left\{r_{1}(t, s ; x, y)+\frac{\mathrm{i} \hbar}{2 m} r_{2}(t, s ; x, y)\right\} f(y) d y,  \tag{7.2}\\
r_{1}=\partial_{t} \mathrm{~S}\left(\gamma_{x, y}^{t, s}\right)+\frac{1}{2 m} \sum_{j=1}^{d}\left\{\partial_{x_{j}} \mathrm{~S}\left(\gamma_{x, y}^{t, s}\right)-\mathrm{A}_{\mathrm{j}}(\mathrm{t}, x)\right\}^{2}+V(\mathrm{t}, x),  \tag{8.2}\\
r_{2}=\frac{d m}{t-s}-\Delta_{x} \mathrm{~S}\left(\gamma_{x, y}^{t, s}\right)+(\nabla . A)(t, x), \tag{9.2}
\end{gather*}
$$

where $\nabla . A=\sum_{j} \partial_{x_{j}} A_{j}$.
Set $\rho=t-s$. Using

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$$
\begin{gathered}
S\left(\gamma_{x, y}^{t, s}\right)=\frac{m|x-y|^{2}}{2(t-s)}+\int_{\gamma_{x, y}^{t, s}} A \cdot d x=\frac{m|x-y|^{2}}{2(t-s)}+(x-y) \cdot \int_{0}^{1} A(s+\theta(t-s), y+\theta(x-y)) d \theta- \\
(t-s) \int_{0}^{1} V(s+\theta(t-s), y+\theta(x-y)) d \theta
\end{gathered}
$$

we have

$$
\begin{aligned}
& \partial_{x_{j}} \mathrm{~S}\left(\gamma_{x, y}^{t, s}\right)-A_{j}(t, x)=\frac{m\left(x_{j}-y_{j}\right)}{\rho}+\int_{0}^{1} A_{j}(s+\theta \rho, y+\theta(x-y))-A_{j}(t, x) d \theta+\sum_{k}\left(x_{k}-y_{k}\right) \\
& \times \int_{0}^{1} \theta \frac{\partial A_{k}}{\partial x_{j}}(s+\theta \rho, y+\theta(x-y)) d \theta-\rho \int_{0}^{1} \theta \frac{\partial V}{\partial x_{j}}(s+\theta \rho, y+\theta(x-y)) d \theta \\
& =\frac{m\left(x_{j}-y_{j}\right)}{\rho}+\int_{0}^{1} A_{j}(t-\theta \rho, x-\theta(x-y))-A_{j}(t, x) d \theta \\
& +\sum_{k}\left(x_{k}-y_{k}\right) \int_{0}^{1}(1-\theta) \frac{\partial A_{k}}{\partial x_{j}}(t-\theta \rho, x-\theta(x-y)) d \theta \\
& \quad-\rho \int_{0}^{1}(1-\theta) \frac{\partial V}{\partial x_{j}}(t-\theta \rho, x-\theta(x-y)) d \theta,
\end{aligned}
$$

and so by the Taylor expansion

$$
\begin{align*}
\partial_{x_{j}} \mathrm{~S}\left(\gamma_{x, y}^{t, s}\right)-A_{j}(t, x)= & \frac{m\left(x_{j}-y_{j}\right)}{\rho}-\frac{1}{2} \sum_{l} \frac{\partial A_{j}}{\partial x_{l}}(t, x)\left(x_{l}-y_{l}\right) \\
& +\frac{1}{2} \sum_{k} \frac{\partial A_{k}}{\partial x_{j}}(t, x)\left(x_{k}-y_{k}\right)+\rho q_{1}\left(t, s ; x, \frac{x-y}{\sqrt{\rho}}\right) \tag{10.2}
\end{align*}
$$

It follows from

$$
-\sum_{j, l}\left(\partial_{x_{l}} A_{j}\right)\left(x_{j}-y_{j}\right)\left(x_{l}-y_{l}\right)+\sum_{j, k}\left(\partial_{x_{j}} A_{k}\right)\left(x_{j}-y_{j}\right)\left(x_{k}-y_{k}\right)=0
$$

that

$$
\begin{equation*}
\frac{1}{2 m} \sum_{j=1}^{d}\left\{\partial_{x_{j}} \mathrm{~S}\left(\gamma_{x, y}^{t, s}\right)-A_{j}(t, x)\right\}^{2}=\frac{m|x-y|^{2}}{2 \rho^{2}}+\sqrt{\rho} q_{2}\left(t, s ; x, \frac{x-y}{\sqrt{\rho}}\right) \tag{11.2}
\end{equation*}
$$

The same arguments show that

$$
\begin{gather*}
\partial_{\mathrm{t}} \mathrm{~S}\left(\gamma_{x, y}^{t, s}\right)=-\frac{m|x-y|^{2}}{2 \rho^{2}}-\mathrm{V}(t, x)+\sqrt{\rho} q_{3}\left(t, s ; x, \frac{x-y}{\sqrt{\rho}}\right)  \tag{12.2}\\
\Delta_{x} \mathrm{~S}\left(\gamma_{x, y}^{t, s}\right)=\frac{d m}{\rho}+(\nabla . A)(t, x)+\sqrt{\rho} q_{4}\left(t, s ; x, \frac{x-y}{\sqrt{\rho}}\right) \tag{13.2}
\end{gather*}
$$

Inserting (11.2) - (13.2) into (7.2) - (9.2), we can complete the proof.

## III. Claims

Corollary (1.3): Assume
$\left(\left|\partial_{\mathrm{x}}^{\alpha} \mathrm{A}_{\mathrm{j}}(\mathrm{t}, \mathrm{x})\right| \leq \mathrm{C}_{\alpha}<x>^{-(1+\delta)},|\alpha| \geq 2,\right)$
and
$\left(\left|\partial_{\mathrm{x}}^{\alpha} \mathrm{V}(\mathrm{t}, \mathrm{x})\right| \leq \mathrm{C}_{\alpha},|\alpha| \geq 2, \quad(\mathrm{t}, \mathrm{x}) \in[0, \mathrm{~T}] \times \mathrm{R}^{\mathrm{d}}.\right)$.

Then we have: (i)

$$
\left|\partial_{x+\varepsilon}^{\alpha} \partial_{x}^{\beta} \phi(\mathrm{s}+\varepsilon, s ; x, x+\varepsilon)\right| \leq \mathrm{C}_{\alpha, \beta},
$$

$$
\begin{equation*}
|\alpha+\beta| \geq 2, \quad \varepsilon \geq 0, x, x+\varepsilon \in R^{d} \tag{1.3}
\end{equation*}
$$

(ii) There exist constants $\rho_{0}>0$ and $\kappa>0$ such that

$$
\begin{equation*}
\inf _{0 \leq \varepsilon \leq \rho_{0}, x, x+\varepsilon} \operatorname{det} \frac{\partial^{2} \phi}{\partial(x+\varepsilon)^{2}}(s+\varepsilon, s ; x, x+\varepsilon) \geq \kappa \tag{2.3}
\end{equation*}
$$

where $\partial^{2} \phi / \partial(x+\varepsilon)^{2}$ is the Hessian in $(x+\varepsilon)$.

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Proof: Let $|\alpha| \geq 1$. Then we have from $\left(\left|\partial_{x}^{\alpha} \mathrm{A}_{j}(t, x)\right| \leq C_{\alpha}<x>^{-(1+\delta)},|\alpha| \geq 2\right.$, $)$,

$$
\left|\partial_{x}^{\alpha} A_{j}(\mathrm{~s}+\varepsilon, x)-\partial_{x}^{\alpha} A_{j}(\mathrm{~s}+\varepsilon, 0)\right| \leq \text { Const. } \int_{0}^{1} \frac{|x|}{\langle\theta x\rangle^{1+\delta}} d \theta \leq \text { Const. } \int_{0}^{\infty} \frac{1}{\langle\theta\rangle^{1+\delta}} d \theta<\infty,
$$

and hence

$$
\begin{equation*}
\left|\partial_{x}^{\alpha} A_{j}(\mathrm{~s}+\varepsilon, x)\right| \leq \mathrm{C}_{\alpha}^{\prime},|\alpha| \geq 1,(\mathrm{~s}+\varepsilon, x) \in[0, T] \times R^{d} \tag{3.3}
\end{equation*}
$$

In the same way we have for $|\alpha| \geq 2$,

$$
\begin{align*}
\mid \sqrt{\rho}(x+\varepsilon) \cdot \int_{0}^{1}\left(\partial_{x}^{\alpha} A\right)(\mathrm{s}+\theta \rho, x & -(1-\theta) \sqrt{\rho}(x+\varepsilon)) d \theta \mid \leq \text { Const. } \int_{0}^{1} \frac{\sqrt{\rho}|x+\varepsilon|}{\langle x-\theta \sqrt{\rho}(x+\varepsilon)\rangle^{1+\delta}} d \theta \\
& \leq \text { Const. } \int_{0}^{\infty} \frac{1}{\langle x-\theta \Omega\rangle^{1+\delta}} d \theta \quad\left(\Omega=\frac{x+\varepsilon}{|x+\varepsilon|}\right)  \tag{4.3}\\
& \leq \text { Const. } \int_{-\infty}^{\infty} \frac{1}{\langle\theta\rangle^{1+\delta}} d \theta=C_{\alpha}^{\prime \prime}<\infty, \quad \varepsilon \geq 0, x \in R^{d}
\end{align*}
$$

where we used $|x-\theta \Omega| \geq|\theta-x . \Omega|$. The inequality (1.3) can be shown from assumptions $\left(\left|\partial_{x}^{\alpha} V(t, x)\right| \leq C_{\alpha},|\alpha| \geq 2, \quad(t, x) \in[0, T] \times\right.$ $R^{d}$. $),\left(\phi(\mathrm{t}, \mathrm{s} ; x, w)=\frac{m}{2}|w|^{2}+\sqrt{\rho} w \cdot \int_{0}^{1} A(s+\right.$ $\theta \rho, x-(1-\theta) \sqrt{\rho} w) d \theta-\rho \int_{0}^{1} V(s+\theta \rho, x-$ $(1-\theta) \sqrt{\rho} w) d \theta, \quad \rho=t-s.),(3.3)$ and (4.3). So can (2.3), because we have $\partial^{2} \phi / \partial(x+\varepsilon)^{2}=$ $(m / 2) I_{d}+O(\varepsilon) . I_{d}$ is the identity matrix.

Lemma (2.3): Set $B_{j k}=-B_{k j}$ for $1 \leq \mathrm{k}<\mathrm{j} \leq$ d and $B_{j j}=0$ for $\mathrm{j}=1,2, \ldots, \mathrm{~d}$. Then we have

$$
\begin{gathered}
\iint_{\Delta} d(A \cdot d X)=(x-y) \cdot\left(\Psi_{1}, \ldots, \Psi_{d}\right), \\
\Psi_{j}=-(t-s) \int_{0}^{1} \int_{0}^{1} \sigma_{1} E_{j}(\tau(\sigma), \zeta(\sigma)) d \sigma_{1} d \sigma_{2} \\
-\sum_{k=1}^{d}\left(\mathrm{z}_{\mathrm{k}}-x_{\mathrm{k}}\right) \int_{0}^{1} \int_{0}^{1} \sigma_{1} B_{j k}(\tau(\sigma), \zeta(\sigma)) d \sigma_{1} d \sigma_{2} \cdot
\end{gathered}
$$

Proof: We have by $(\tau(\sigma), \zeta(\sigma))=(1-$ $\left.\sigma_{2}\right)\left\{\left(1-\sigma_{1}\right)(t, z)+\sigma_{1}(s, x)\right\}+\sigma_{2}\{(1-$
$\left.\left.\sigma_{1}\right)(t, z)+\sigma_{1}(s, y)\right\}=\left(t-\sigma_{1}(t-s), z+\sigma_{1}(x-\right.$ $\left.z)+\sigma_{1} \sigma_{2}(y-x)\right) \in R^{d+1}$.,

$$
\begin{gather*}
\iint_{\Delta} E_{j} d t \wedge d x_{j}=\int_{0}^{1} \int_{0}^{1} E_{j}(\tau(\sigma), \zeta(\sigma)) \operatorname{det} \frac{\partial\left(\tau, \zeta_{j}\right)}{\partial\left(\sigma_{1}, \sigma_{2}\right)} d \sigma_{1} d \sigma_{2}=(t-s)\left(x_{j}-y_{j}\right) \int_{0}^{1} \int_{0}^{1} \sigma_{1} E_{j} d \sigma_{1} d \sigma_{2},  \tag{7.3}\\
\iint_{\Delta} B_{j k} d x_{j} \wedge d x_{k}=\int_{0}^{1} \int_{0}^{1} B_{j k} \operatorname{det} \frac{\partial\left(\zeta_{j}, \zeta_{k}\right)}{\partial\left(\sigma_{1}, \sigma_{2}\right)} d \sigma_{1} d \sigma_{2} \\
-\left\{\left(x_{k}-y_{k}\right)\left(x_{j}-z_{j}\right)-\left(x_{j}-y_{j}\right)\left(x_{k}-z_{k}\right)\right\} \int_{0}^{1} \int_{0}^{1} \sigma_{1} B_{j k} d \sigma_{1} d \sigma_{2}, \tag{8.3}
\end{gather*}
$$

and hence from $\operatorname{Lemma}(1.2 .7)$ [5],

$$
\begin{gathered}
\iint_{\Delta} d(A \cdot d X)=-(t-s) \sum_{j}\left(x_{j}-y_{j}\right) \int_{0}^{1} \int_{0}^{1} \sigma_{1} E_{j} d \sigma_{1} d \sigma_{2} \\
-\sum_{1 \leq j<k \leq d}\left\{\left(x_{k}-y_{k}\right)\left(x_{j}-z_{j}\right)-\left(x_{j}-y_{j}\right)\left(x_{k}-z_{k}\right)\right\} \int_{0}^{1} \int_{0}^{1} \sigma_{1} B_{j k} d \sigma_{1} d \sigma_{2} \\
=-(t-s) \sum_{j=1}^{d}\left(x_{j}-y_{j}\right) \int_{0}^{1} \int_{0}^{1} \sigma_{1} E_{j} d \sigma_{1} d \sigma_{2}+\sum_{j, k=1}^{d}\left(x_{j}-y_{j}\right)\left(x_{k}-z_{k}\right) \int_{0}^{1} \int_{0}^{1} \sigma_{1} B_{j k} d \sigma_{1} d \sigma_{2} .
\end{gathered}
$$

Thus Lemma (2.3) could be proved.

## IV. Conclusion

Was defined Sobolev spaces and an OrnsteinUhlenbeck operator on the loop space. We find some
functionals which belong to all the Sobolev spaces We study two versions of the Sobolev calculus on the free loop space which are both invariant under rotations of loops. We work on $\mathbb{R}^{d}$ with metric $\sum \mathrm{g}_{i j} d x^{i} d x^{j}$, where the $\mathrm{g}_{\mathrm{ij}}$ are smooth bounded functions. These Hilbert spaces form a measurable

|  | ISRA (India) | $=6.317$ | SIS (USA) | $=0.912$ | ICV (Poland) | $=6.630$ |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| Impact Factor: | ISI (Dubai, UAE) $=1.582$ | PИHL (Russia) $=\mathbf{0 . 1 2 6}$ | PIF (India) | $=1.940$ |  |  |
| GIF (Australia) | $=0.564$ | ESJI (KZ) | $=9.035$ | IBI (India) | $=4.260$ |  |
|  | $=1.500$ | SJIF (Morocco) $=7.184$ | OAJI (USA) | $=0.350$ |  |  |

field of tangent Hilbert spaces on the loop space and they will play the role of the tangent spaces of the loop space. The basic tool in setting up this Sobolev calculus is integration by parts formulas.

In $[13,14]$ gave the rigorous meaning of the Feynman path integral for a class of potentials, adopting the formulation through piecewise classical paths. In [15] this result was generalized for a wide class of potentials. We study the formulation of the Feynman path integral through broken line paths.

This formulation is very familiar to us and well known to be useful.

Using the ideas in the theory of difference methods and the theory of pseudo-differential operators, we show rigorously for some class of potentials that this formulation is well defined and that this Feynman path integral gives the probability amplitude, i.e., the solution of the Schrödinger equation.

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