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# FINITE DIMENSIONAL APPROXIMATION AND WIENER MEASURE 


#### Abstract

We introduce the notion of the Finite Dimensional Approximation and Wiener Measure, Differential Calculus on the Riemannian Path Space and The maps $\rho \mathcal{P}$ and $\tilde{\rho} \mathcal{P}$ The matrix $G_{\mathcal{P}}^{\mathcal{F}_{\mathcal{P}}}$. We prove the finite dimensional version of the intertwinning formula for the derivative Theorem (6.1.8) [1] and the finite dimensional integration by parts formula Theorem (3.2).


Key words: Riemannian manifold, Itô filtration, path space, Ornstein-Uhlenbeck operator, Gaussian measure, Wiener measures, Brownian motion.

## Language: English

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## Introduction

In [2] the foundations of a Riemannian geometry on $\mathrm{W}(M)$ have been defined (cf. also [3]). This leads to an extension of the initial notion of tangent space.This work is an attempt to approximate systematically the geometrical objects on the path space by finite dimensional ones. This procedure justifies a posteriori and in some sense the choice of the Markovian connection. In particular, it allows to construct a process on the frame bundle of the path space which corresponds to the lift of the Ornstein-Ulhenbeck-Driver-Röckner process. The lifted process plays a crucial role in the development of the stochastic calculus of variations on the path space [4]. For other finite dimensional approaches to analysis and geometry on path spaces we refer to $[5,6,7,8]$.

We give the basic definitions of differential geometry on the path space. We construct the finite dimensional geometrical objects based on finite
partitions of the time interval and in particular we construct a discretized version of Markovian connection. We prove the finite dimensional version of the intertwinning formula for the derivative (Theorem (6.1.8)) and the finite dimensional integration by parts formula (Theorem (6.1.11)). As the mesh of the partitions goes to zero, we derive in an independent way, correspondingly, statement 2.6 of [2] and Bismut's formula. We devoted to finite dimensional approximation of the OrnsteinUhlenbeck operator, associated process and corresponding semigroup.

Let $\left(M,\langle\cdot, \cdot\rangle_{m}\right)$ be a compact Riemannian manifold of dimension $d$, where $\langle\cdot, \cdot\rangle_{m}$ is the Riemannian metric. On this Riemannian manifold we consider the Levi-Civita connection associated with $\langle\cdot, \cdot\rangle_{m}$. Let $\mathrm{O}(M)$ denote the bundle of orthogonal frames over M, namely

$$
O(M):=\left\{(m, r): r \text { is a Euclidean isometry from } \mathbb{R}^{d} \text { into } T_{m}(M), m \in M\right\}
$$

Then $O(M)$ is a parallelized manifold.
Definition (1.1): (Tangent Space): Let $\sigma \in$ $H^{(n)}(M), b=I_{n}^{-1}(\sigma), r$ the horizontal lift of $\sigma$. For $z \in H$, then $Z(s):=t_{s \leftarrow 0}^{\sigma}(z(s)) \in T_{\sigma} H^{(n)}(M)$ if and
only if

$$
\ddot{z}(s)=\Omega_{r(s)}(\dot{b}(s), z(s)) \dot{b}(s) \quad \text { on } I \backslash P .
$$

This tangent space is inherited from the tangent space of the Gaussian vector space $H^{(n)}$ through the

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Itô mapping $I_{n}$ (cf. [6, Proposition 4.4]).
Let $\quad M^{(n)}:=M^{n} \quad$ and $\quad \pi_{n}^{W}: W(M) \mapsto$ $M^{(n)}\left(\right.$ resp. $\left.\pi_{n}^{X}: X \mapsto H^{(n)}\right)$ denote the projection

$$
\begin{gathered}
\pi_{n}^{W}(p):=\left(p\left(s_{1}\right), \ldots, p\left(s_{n}\right)\right) \\
\left(\operatorname{resp} . \pi_{n}^{X}(b):=\left(b\left(s_{1}\right), \ldots, b\left(s_{n}\right)\right)\right)
\end{gathered}
$$

On this space there is a natural tangent space $T\left(M^{(n)}\right)=T(M)^{n}$ which is different from the
previous one on $H^{(n)}(M)$. We shall establish a relation between these two tangent spaces.

We can endow $H^{(n)}(M)$, with a Gaussian measure $v_{n}$ such that $v_{n} \circ I_{n}=\mu_{n}$, where $\mu_{n}=\mu \circ$ $\left(\pi_{n}^{X}\right)^{-1}$ is the finite dimensional Gaussian measure on $H^{(n)}$.

For $\varepsilon \in[0,1]$, let

$$
\begin{aligned}
M_{\varepsilon}^{(n)} & :=\left\{v \in M^{(n)}: d\left(v_{i}, v_{i+1}\right)<\zeta_{\varepsilon}, \text { for } i=0,1, \ldots, n-1\right\}, \\
H_{\varepsilon}^{(n)}(M) & :=\left\{\sigma \in H^{(n)}(M): \int_{s_{i}}^{s_{i+1}}|\dot{\sigma}(s)| d s<\zeta_{\varepsilon}, \quad \text { for } i=0,1, \ldots, n-1\right\}, \\
H_{\varepsilon}^{(n)} & :=\left\{z \in H^{(n)}:\left\|\Delta_{i} z\right\|<\zeta_{\varepsilon}, \text { for } i=0,1, \ldots, n-1\right\},
\end{aligned}
$$

where

$$
\begin{equation*}
\zeta_{\varepsilon}:=\varepsilon\left(\rho \wedge 4 / K_{\Omega}\right) \tag{1.1}
\end{equation*}
$$

and $\rho$ is the injectivity radius of $M, K_{\Omega}=$ $\sup _{r \in O(M)}\left\|\Omega_{r}\right\|<\infty$.
$M_{\varepsilon}^{(n)}$ is an open subset of $M^{(n)}$ and therefore is a differentiable manifold. We associate to $v \in M_{\varepsilon}^{(n)}$ the piecewise geodesic curve $\sigma_{v}$ defined by linking the points $v_{i}, v_{i+1}$ by the minimizing geodesic. For $v \in M_{\varepsilon}^{(n)}$, we consider the map

$$
\left[\Theta_{v}^{(n)}\right]^{-1}: H^{(n)} \mapsto T_{v}\left(M_{\varepsilon}^{(n)}\right)
$$

given by $Z\left(s_{i}\right):=t_{s_{i} \leftarrow 0}^{\sigma_{v}}\left(z\left(s_{i}\right)\right) \in T_{v_{i}}(M)$,
$i=1, \ldots, n$, where $z \in H^{(n)}$. Then $\Theta^{(n)}$ defines a parallelism on $M_{\varepsilon}^{(n)}$.

Definition (1.2): For any smooth vector fields $Y, Z \in T\left(M_{\varepsilon}^{(n)}\right)$, put

$$
\begin{gathered}
\frac{d}{d s}\left(\nabla_{Y}^{(n)} Z\right)^{\alpha}\left(v, s^{-}\right):=\mathrm{D}_{Y}^{(n)} \dot{z}^{\alpha}\left(s^{-}\right) \\
+\int_{0}^{s^{-}} \Omega_{\gamma \lambda \beta}^{\alpha}\left(\sigma_{v}(\tau)\right) y^{\gamma}(\tau) d\left[I_{n}^{-1}\left(\sigma_{v}\right)\right]^{\lambda}(\tau) \cdot \dot{z}^{\beta}\left(s^{-}\right) . \\
\text {Here for } f \in C^{\infty}\left(M_{\varepsilon}^{(n)}\right)
\end{gathered}
$$

$$
\left(\mathrm{D}_{s, \alpha}^{(n)} f\right)(v):=\sum_{k=1}^{n} 1_{s<s_{k}}\left\langle t_{0 \leftarrow s_{k}}^{\sigma_{v}} \partial_{k} f, \varepsilon_{\alpha}\right\rangle_{m_{0}}
$$

and

$$
\begin{gathered}
\mathrm{D}_{Y}^{(n)} f:=\int_{0}^{1} \mathrm{D}_{s, \alpha}^{(n)} f \cdot \dot{y}^{\alpha}(s) d s= \\
\sum_{k=1}^{n}\left\langle\partial_{k} f, Y\left(s_{k}\right)\right\rangle_{v_{k}}=Y f .
\end{gathered}
$$

Heuristic path integrals such as those in Eq. (6.48)[12] have proven themselves useful and arise often in physics literature. Particularly, one can interpret this path integral as the path integral quantization of the Hamiltonian on M. Much of the current interest concerning path integrals in physics began with Feynman in [13] and has since grown deeply. The role of path integrals in quantum mechanics is surveyed by Gross in [14] and detailed more by Feynman and Hibbs in [15] as well as Glimm and Jaffe in [16].

For the partition $\mathcal{P}=\left\{0=s_{0}<s_{1}<\cdots<\right.$ $\left.s_{n}=1\right\}$, define the finite-dimensional subspace $H_{\mathcal{P}}(M)$ of $W(M)$ by

$$
\begin{equation*}
H_{\mathcal{P}}(M)=\{\sigma \in W(M): \sigma \text { is piecewise geodesic with respect to } \mathcal{P}\} . \tag{1.2}
\end{equation*}
$$

We make $H_{\mathcal{P}}(M)$ into a Riemannian manifold by endowing it with the $L^{2}$ metric $G_{\mathcal{P}}$, defined by

$$
\begin{equation*}
G_{\mathcal{P}}(X, Y)=\int_{0}^{1} g(X(s), Y(s)) d s \tag{1.3}
\end{equation*}
$$

where we are making the natural identification of the tangent space $T_{\sigma} H_{\mathcal{P}}(M)$ with the piecewise Jacobi fields along $\sigma$ in $M$. From here we define the approximate Wiener measure $v_{G_{\mathcal{P}}}$ on $H_{\mathcal{P}}(M)$ by

$$
\begin{equation*}
d v_{G_{\mathcal{P}}}=\frac{1}{Z_{G_{\mathcal{P}}}} e^{-\frac{1}{2} \int_{0}^{1}\left\|\sigma^{\prime}(s)\right\|^{2} d s} d V o 1_{G_{\mathcal{P}}} \tag{1.4}
\end{equation*}
$$

where $\operatorname{Vol}_{G_{\mathcal{P}}}$ is the Riemannian volume form given by $G_{\mathcal{P}}$ and $Z_{G_{\mathcal{P}}}$ is a normalization constant which forces $v_{G_{\mathcal{P}}}$ to be a probability measure in the case that $M=\mathbb{R}^{d}$. With the matrix $\mathcal{L}_{\mathcal{P}}$ introduced below in Eq. (6.97)[12],

$$
\begin{equation*}
Z_{G_{\mathcal{P}}}=\sqrt{\operatorname{det} \mathcal{L}_{\mathcal{P}}} \prod_{i=1}^{n}\left(2 \pi \Delta_{i} s\right)^{d / 2} \tag{1.5}
\end{equation*}
$$

It is well known that the Wiener measure on $W\left(\mathbb{R}^{d}\right)$ is the law of an $\mathbb{R}^{d}$-valued Brownian motion, and conversely, the evaluation maps $b_{s}(\omega)=\omega(s)$ on $W\left(\mathbb{R}^{d}\right)$ are an $\mathbb{R}^{d}$-valued Brownian motion under the Wiener measure.

In what follows we use the symbols $\mu$ and $v$ to denote the Wiener measures on $W\left(\mathbb{R}^{d}\right)$ and $W(M)$ respectively. Although we will consider several probability spaces, the symbol $\mathbb{E}$ will be used solely for expectation on the probability space $\left(W\left(\mathbb{R}^{d}\right), \mu\right)$.

The piecewise approximation of Brownian motion with respect to the partition $\mathcal{P}$ are the maps $b_{s}^{\mathcal{P}}: W\left(\mathbb{R}^{d}\right) \rightarrow H_{\mathcal{P}}\left(\mathbb{R}^{d}\right)$ with $s \in[0,1]$ given by

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| JIIF | $=1.500$ | SJIIF (Morocco) | $=7.184$ | OAJI (USA) | $=0.350$ |

$$
\begin{equation*}
b_{s}^{\mathcal{P}}:=\sum_{i=1}^{n} 1_{J_{i}}(s)\left[\frac{\Delta_{i} b}{\Delta_{i} s}\left(s-s_{i-1}\right)+b_{s_{i-1}}\right] \tag{1.6}
\end{equation*}
$$

Here and forevermore $\Delta_{i} b=b_{s_{i}}-b_{s_{i-1}}$, and $J_{i}=\left(s_{i-1}, s_{i}\right]$ when $i>1$ and $J_{1}=\left[0, s_{1}\right)$. It is
important to note that $\left.b_{s}\right|_{H_{\mathcal{P}}\left(\mathbb{R}^{d}\right)}=\left.b_{s}^{\mathcal{P}}\right|_{H_{\mathcal{P}}\left(\mathbb{R}^{d}\right)}$.
This is a convenient place to introduce the Cameron-Martin subspace $H(M)$ of the Wiener space, which is the collection of absolutely continuous paths with finite energy,

$$
\begin{equation*}
H(M)=\left\{\sigma \in W(M): \sigma \text { is absolutely continuous, } \int_{0}^{1}\left\|\sigma^{\prime}(s)\right\|^{2} d s<\infty\right\} \tag{1.7}
\end{equation*}
$$

The Cameron-Martin space is a Hilbert space and $\left(i, H\left(\mathbb{R}^{d}\right), W\left(\mathbb{R}^{d}\right)\right)$ is the prototype for an abstract Wiener space, where $i: H\left(\mathbb{R}^{d}\right) \rightarrow W\left(\mathbb{R}^{d}\right)$ is the canonical injection.

The tangent space $T_{\sigma} H_{\mathcal{P}}(M)$ is identified with the continuous piecewise Jacobi fields along $\sigma$.

We introduce the measure $v_{S_{\mathcal{P}}}$ in Eq. (6.60) and $\mu_{S_{\mathcal{P}}}$, where $\mu_{S_{\mathcal{P}}}$ is simply realization of $v_{\mathcal{S}_{\mathcal{P}}}$ in the flat case $M=\mathbb{R}^{d}$.

## II. Preliminaries

We consider the orthogonal basis of $H^{(n)}$ defined in Theorem (6.1.24)[1], and the corresponding parallelized vector fields $H_{i, \alpha}(v, s)=$ $t_{s \leftarrow 0}^{\sigma_{v}} h_{i, \alpha}$.

We denote by $B_{i, \alpha}$ the horizontal lift of $H_{i, \alpha}$ through the Markovian connection $\nabla^{(n)}$ (cf. [10, 11]). Let

$$
\Delta_{o\left(M_{\varepsilon}^{(n)}\right)}:=-\sum_{\alpha, i} B_{i, \alpha} B_{i, \alpha}+\sum_{\alpha, i} \delta^{(n)}\left(H_{i, \alpha}\right) \cdot B_{i, \alpha}
$$

Then $\Delta_{o\left(M_{\varepsilon}^{(n)}\right)}$ is the lift of $L^{(n)}$ to the frame bundle.

Theorem (2.1): For any $f \in C^{\infty}\left(M_{\varepsilon}^{(n)}\right)$, we have

$$
\Delta_{o\left(M_{\varepsilon}^{(n)}\right)}(f \circ \pi)=\left(L^{(n)} f\right) \circ \pi
$$

Here $\pi$ is the bundle projection.
Proof. It is a direct consequence of the identity $B_{i, \alpha}(f \circ \pi)=\left(H_{i, \alpha} f\right) \circ \pi$.

For any vector field Z on $M_{\varepsilon}^{(n)}$, we use $F_{Z}$ to denote its scalarization, i.e. $F_{Z}(r)=r^{-1}(Z) \in H^{(n)}$.

Theorem (2.2): The following commutation relation holds:

$$
\Delta_{o\left(M_{\varepsilon}^{(n)}\right)} F_{Z}=F_{\Delta^{(n)} Z_{Z}}
$$

where

$$
\Delta^{(n)} Z:=\sum_{\alpha, i} \nabla_{h_{i, \alpha}}^{(n)} \nabla_{h_{i, \alpha}}^{(n)} Z+\delta^{(n)}\left(h_{i, \alpha}\right) \nabla_{h_{i, \alpha}}^{(n)} Z
$$

Proof. It is deduced from $B_{i, \alpha} F_{Z}=F_{\nabla_{h_{i, \alpha}}^{(n)} Z}$.
Now we define a Dirichlet form as follows:

$$
\begin{gathered}
\mathcal{E}_{H}^{(n)}\left(Z_{1}, Z_{2}\right)=E^{v_{n, \varepsilon}}\left(\sum_{\alpha, i}\left\langle\nabla_{h_{i, \alpha}}^{(n)} Z_{1}, \nabla_{h_{i, \alpha}}^{(n)} Z_{2}\right\rangle_{M_{\varepsilon}^{(n)}}\right), \\
Z_{1}, Z_{2} \in T\left(M_{\varepsilon}^{(n)}\right)
\end{gathered}
$$

As a consequence of the relation

$$
\begin{aligned}
\mathrm{D}_{h_{i, \alpha}}^{(n)}\left\langle Z_{1}, Z_{2}\right\rangle_{M_{\varepsilon}}^{(n)} & =\left\langle\nabla_{h_{i, \alpha}}^{(n)} Z_{1}, Z_{2}\right\rangle_{M_{\varepsilon}^{(n)}} \\
& +\left\langle Z_{1}, \nabla_{h_{i, \alpha}}^{(n)} Z_{2}\right\rangle_{M_{\varepsilon}^{(n)}}^{(n)}
\end{aligned}
$$

and integration by parts.
Proposition (2.3): For $s \in[0, \Delta]$,

$$
\begin{gather*}
\left\|V_{i+1}^{\mathcal{P}}(s)^{\operatorname{tr}} V_{i+1}^{\mathcal{P}}(s)-(\Delta-s)^{2} I\right\| \leq 3(\Delta-s)^{2}\left(\cosh \left(2 \sqrt{K_{i}^{\mathcal{P}}} \Delta\right) \cosh \left(8 \sqrt{K_{i+1}^{\mathcal{P}}} \Delta\right)-1\right)  \tag{2.1}\\
\left\|S_{i}^{\mathcal{P}}(s)^{\operatorname{tr}} S_{i}^{\mathcal{P}}(s)-s^{2} I\right\| \leq 3 s^{2}\left(\cosh \left(2 \sqrt{K_{i}^{\mathcal{P}}} \Delta\right)-1\right) \tag{2.2}
\end{gather*}
$$

and

$$
\begin{equation*}
\left\|V_{i+1}^{\mathcal{P}}(s)^{\operatorname{tr}} S_{i+1}^{\mathcal{P}}(s)-(\Delta-s) s I\right\| \leq 3 s(\Delta-s)\left(\cosh \left(\sqrt{K_{i}^{\mathcal{P}}} \Delta\right) \cosh \left(5 \sqrt{K_{i+1}^{\mathcal{P}} \Delta}\right)-1\right) \tag{2.3}
\end{equation*}
$$

Proof. We apply Lemma (6.2.19)[12]. For operators $A$ and $B$ and real numbers $a$ and $b$,

$$
\begin{gathered}
A^{t r} B-a b I=\left(A^{t r}-a I\right)(B-b I)+a(B-b I) \\
+b\left(A^{t r}-a I\right)
\end{gathered}
$$

The asserted inequalities now follow with judicious choices for $A$ and $B$ as well as Eqs. (3.6) and (3.7) along with the fact that $s / \Delta \leq 1$.

Applying Proposition (2.3) to Eqs (6.127)[12] and (6.128)[12] gives the estimates we need on $\mathcal{R}_{\mathcal{P}}$ to continue forward.

Proposition (2.4): Let $Y_{\mathcal{P}}$ be as in Eq. (6.177) [12], $\tau_{\mathcal{P}}$ be as in Eq. (6.178) [12], and $\tau_{G}$ be as in Eq.
(6.180)[12]. There is a constant $\mathrm{C}=\mathrm{C}$ ( d , curvature) $<\infty$ such that,

$$
\begin{array}{r}
\int_{H_{\mathcal{P}}^{\varepsilon}\left(\mathbb{R}^{d}\right)}\left|e^{Y_{\mathcal{P}}(\omega)}-e^{-\tau_{G} \int_{0}^{1} \operatorname{scal}(\phi(\omega)(s))}\right| d \mu_{S_{\mathcal{P}}}(\omega) \leq \\
C\left(\sqrt{\left|\tau_{\mathcal{P}}-\tau_{G}\right|}+\Delta^{1 / 4}\right) . \tag{2.4}
\end{array}
$$

Proof. Breaking the integrand into pieces we consider

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$$
\begin{aligned}
\underbrace{e^{Y_{\mathcal{P}}(\omega)}-e^{-\tau_{G} \mathcal{R}_{\mathcal{P}}}}_{I} & +\underbrace{e^{-\tau_{G} \mathcal{R}_{\mathcal{P}}}-e^{-\tau_{G} S_{\mathcal{P}}}}_{I I} \\
& +\underbrace{e^{-\tau_{G} S_{\mathcal{P}}}-e^{-\tau_{G} \int_{0}^{1} S \operatorname{cal}(\phi(\omega)(s))}}_{I I I}
\end{aligned}
$$

Let $\Lambda=\Lambda$ (curvature) $<\infty$ be given such that

$$
\int_{H_{\mathcal{P}}^{\delta}\left(\mathbb{R}^{d}\right)}|I I| \leq e^{\tau_{G} \Lambda} \int_{H_{\mathcal{P}}\left(\mathbb{R}^{d}\right)}\left|e^{-\tau_{G}\left(\mathcal{R}_{\mathcal{P}}-S_{\mathcal{P}}\right)}-1\right| \leq C\left(e^{C \Delta}-1\right)^{1 / 2} .
$$

Similarly, with

$$
\left|e^{-\tau_{G} S_{\mathcal{P}}}-e^{-\tau_{G} \int_{0}^{1} S \operatorname{cal}(\phi(\omega)(s))}\right| \leq e^{\tau_{G} \Lambda}\left(\exp \left\{\tau_{G}\left|S_{\mathcal{P}}-\int_{0}^{1} \operatorname{Scal}(\phi(\omega)(s)) d s\right|\right\}-1\right)
$$

another application of Lemma (6.2.48) [12] to the right-hand side along with Lemma (6.2.6) [12] gives $\int|I I I| \leq C \Delta^{1 / 4}$.

What remains then is to bound $\int|I|$. To start, we will assume that $\Lambda$ is also a bound on Ric so that
$\left|\left\langle\operatorname{Ric}_{u\left(s_{i-1}\right)} \Delta_{i} b, \Delta_{i} b\right\rangle\right| \leq \Lambda\left\|\Delta_{i} b\right\|^{2}$ for each $i=$
$\mid$ Scal $\mid \leq \Lambda$. Then,
$\left|e^{-\tau_{G} \mathcal{R}_{\mathcal{P}}}-e^{-\tau_{G} S_{\mathcal{P}}}\right| \leq e^{\tau_{G} \Lambda}\left|e^{-\tau_{G}\left(\mathcal{R}_{\mathcal{P}}-S_{\mathcal{P}}\right)}-1\right|$.
Now applying Lemma (6.2.48)[12] and Lemma (6.2.5)[12], $1,2, \ldots, n$. From here,

$$
\left|\mathcal{R}_{\mathcal{P}}\right| \leq \Lambda \sum_{i=1}^{n}\left\|\Delta_{i} b\right\|^{2} \text { and }\left|\partial \mathcal{R}_{\mathcal{P}}\right| \leq \Lambda\left(\left\|\Delta_{1} b\right\|^{2}+\left\|\Delta_{n-1} b\right\|^{2}+\left\|\Delta_{n} b\right\|^{2}\right)
$$

along with Eq. (3. 4), Eq. (6.200) in Lemma
(6.2.46)[12], and Theorem (6.2.4)[12] we have

$$
\begin{equation*}
\int_{H_{\mathcal{P}}^{\varepsilon}\left(\mathbb{R}^{d}\right)} e^{2 \tau_{G}\left|\mathcal{R}_{\mathcal{P}}\right|} d \mu_{S_{\mathcal{P}}} \leq 2 \tau_{G} \Lambda \sum_{i=1}^{n} \mathbb{E}\left[\left\|\Delta_{i} b\right\|^{2} e^{2 \tau_{G} \Lambda \sum_{j=1}^{n}\left\|\Delta_{j} b\right\|^{2}}\right]+1 \leq C . \tag{2.5}
\end{equation*}
$$

Along these same lines, from Eq. (6.200)[12],

$$
\begin{aligned}
\int_{H_{\mathcal{P}}^{\varepsilon}\left(\mathbb{R}^{d}\right)}\left|\left(\tau_{G}-\tau_{\mathcal{P}}\right) \mathcal{R}_{\mathcal{P}}\right| e^{\left|\left(\tau_{G}-\tau_{\mathcal{P}}\right) \mathcal{R}_{\mathcal{P}}+\tau_{\mathcal{P}} \partial \mathcal{R}_{\mathcal{P}}\right|} d \mu_{S_{\mathcal{P}}} \leq \mathbb{E}\left[\left|\left(\tau_{G}-\tau_{\mathcal{P}}\right) \mathcal{R}_{\mathcal{P}}\right| e^{\left|\left(\tau_{G}-\tau_{\mathcal{P}}\right) \mathcal{R}_{\mathcal{P}}+\tau_{\mathcal{P}} \partial \mathcal{R}_{\mathcal{P}}\right|}\right] \\
\leq\left|\tau_{G}-\tau_{\mathcal{P}}\right| \Lambda \sum_{i=1}^{n} \mathbb{E}\left[\left\|\Delta_{i} b\right\|^{2} e^{2 \Lambda \sum_{j=1}^{n}\left\|\Delta_{j} b\right\|^{2}}\right] \leq C\left(\left|\tau_{G}-\tau_{\mathcal{P}}\right|\right)
\end{aligned}
$$

and arguing similarly using Eq. (6.199)[12],

$$
\int_{H_{\mathcal{P}}^{\varepsilon}\left(\mathbb{R}^{d}\right)}\left|\tau_{\mathcal{P}} \partial \mathcal{R}_{\mathcal{P}}\right| e^{\left|\left(\tau_{G}-\tau_{\mathcal{P}}\right) \mathcal{R}_{\mathcal{P}}+\tau_{\mathcal{P}} \partial \mathcal{R}_{\mathcal{P}}\right|} d \mu_{S_{\mathcal{P}}} \leq \mathbb{E}\left[\left|\tau_{\mathcal{P}} \partial \mathcal{R}_{\mathcal{P}}\right| e^{\left|\left(\tau_{G}-\tau_{\mathcal{P}}\right) \mathcal{R}_{\mathcal{P}}+\tau_{\mathcal{P}} \partial \mathcal{R}_{\mathcal{P}}\right|}\right] \leq C \Delta
$$

In particular,

$$
\begin{equation*}
\mathbb{E}\left[\left|\left(\tau_{G}-\tau_{\mathcal{P}}\right) \mathcal{R}_{\mathcal{P}}+\tau_{\mathcal{P}} \partial \mathcal{R}_{\mathcal{P}}\right| e^{\left|\left(\tau_{G}-\tau_{\mathcal{P}}\right) \mathcal{R}_{\mathcal{P}}+\tau_{\mathcal{P}} \partial \mathcal{R}_{\mathcal{P}}\right|}\right] \leq C\left(\left|\tau_{G}-\tau_{\mathcal{P}}\right|+\Delta\right) \tag{2.6}
\end{equation*}
$$

With Eqs. (6.182)[12] and (3. 4), Lemma (6.2.48)[12] implies $\int|I| \leq C\left(\left|\tau_{G}-\tau_{\mathcal{P}}\right|+\Delta\right)^{1 / 2}$. Combining the bounds on $\int|I|, \int|I I|$, and $\int|I I I|$ concludes the proof.

## III. Claims

Definition (3.1): On $M_{\varepsilon}^{(n)}$ a Riemannian metric is defined by the condition that $\Theta_{v}^{(n)}$ is an isometry of $T_{v}\left(M_{\varepsilon}^{(n)}\right)$ onto $H^{(n)}$.

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| GIF (Australia) | $=0.564$ | ESJI (KZ) | $=9.035$ | IBI (India) | $=4.260$ |  |
|  | $=1.500$ | SJIF (Morocco) | $=7.184$ | OAJI (USA) | $=0.350$ |  |

Hereafter, we shall use $\langle\cdot, \cdot\rangle_{M_{\varepsilon}^{(n)}}$ or simply $\langle\cdot, \cdot\rangle$ to denote this metric.

Note that under the map $\pi_{n}^{W}, I_{n}$, we can identify $M_{\varepsilon}^{(n)}, H_{\varepsilon}^{(n)}(M)$ and $H_{\varepsilon}^{(n)}$. In particular, we have

$$
d\left(v_{i}, v_{i+1}\right)=\int_{s_{i}}^{s_{i+1}}\left|\dot{\sigma}_{v}(s)\right| d s=\left\|\Delta_{i} b_{v}\right\|
$$

where $\dot{b}_{v}(s)=t_{0 \leftrightarrow s}^{\sigma_{v}} \dot{\sigma}_{v}(s)$. It is sometimes convenient not to distinguish $M_{\varepsilon}^{(n)}$ and $H_{\varepsilon}^{(n)}(M)$.

We define the following Markovian connection which is compatible with $\langle\cdot, \cdot\rangle_{M_{\varepsilon}^{(n)}}$ on the finite manifold $M_{\varepsilon}^{(n)}$

Theorem (3.2): For every vector field $z: M_{\varepsilon}^{(n)} \mapsto H^{(n)}$ such that $z^{\alpha}\left(s_{i}\right) \in C_{r}^{1}\left(M_{\varepsilon}^{(n)}\right)$ for $\alpha=1, \ldots, d, i=1, \ldots, n$, we have

$$
\int_{M_{\varepsilon}^{(n)}} D_{z}^{(n)} f d v_{n, \varepsilon}=\int_{M_{\varepsilon}^{(n)}} f \cdot \delta^{(n)} Z d v_{n, \varepsilon}
$$

where

$$
\begin{equation*}
\left(\delta^{(n)} z\right)(\sigma)=\sum_{\alpha} \int_{0}^{1} \dot{z}^{\alpha}\left(t^{-}\right) d\left[I_{n}^{-1}(\sigma)\right]^{\alpha}(t)-\int_{0}^{1} D_{t, \alpha}^{X} \dot{\hat{z}}^{\alpha}\left(t^{-}\right) d t-\frac{2 D_{z}^{(n)} \hat{\varphi}_{n}}{\hat{\varphi}_{n}} \tag{3.1}
\end{equation*}
$$

and $\hat{z}$ is given in (6.9)[1].
Proof. The idea of the proof is to push back all divergence computations to the flat finite dimensional

Gaussian vector space $H^{(n)}$.
For any $f \in C_{r}^{\infty}\left(M_{\varepsilon}^{(n)}\right)$, we have

$$
\int_{M_{\varepsilon}^{(n)}} D_{z}^{(n)} f d v_{n, \varepsilon}=\int_{H_{\varepsilon}^{(n)}(M)} D_{z}^{(n)} f \cdot \hat{\varphi}_{n}^{2} d v_{n}=\int_{H_{\varepsilon}^{(n)}(M)} D_{z}^{(n)}\left(f \cdot \hat{\varphi}_{n}^{2}\right) d v_{n}-\int_{H_{\varepsilon}^{(n)}(M)} f D_{Z}^{(n)} \hat{\varphi}_{n}^{2} d v_{n}
$$

The function $\left(f \cdot \hat{\varphi}_{n}^{2}\right) \circ I_{n}$ belongs to $C^{\infty}\left(H^{(n)}\right)$.
We define

$$
\phi_{n} \in C^{\infty}\left(H^{(n)}\right) \text { satisfying }
$$

$$
\begin{cases}\varphi_{n}(b)=1, & b \in H_{\varepsilon}^{(n)}  \tag{3.2}\\ \varphi_{n}(b)=0, & b \notin H_{\varepsilon^{\prime \prime}}^{(n)}\end{cases}
$$

$$
\begin{aligned}
& \int_{H_{\varepsilon}^{(n)}(M)} D_{z}^{(n)}\left(f \cdot \hat{\varphi}_{n}^{2}\right) d v_{n} \\
& =\int_{H_{\varepsilon}^{(n)}} D_{\hat{z}}^{X}\left(\left(f \cdot \hat{\varphi}_{n}^{2}\right) \circ I_{n}\right) d \mu_{n} \\
& =\int_{H^{(n)}} D_{\phi_{n} \cdot \hat{z}}^{X}\left(\left(f \cdot \hat{\varphi}_{n}^{2}\right) \circ I_{n}\right) d \mu_{n} \\
& =\int_{X}\left[D_{\phi_{n} \cdot \hat{z}}^{X}\left(\left(f \cdot \hat{\varphi}_{n}^{2}\right) \circ I_{n}\right)\right] \circ \pi_{n}^{X} d \mu \\
& =\int_{X}\left[\left(f \cdot \hat{\varphi}_{n}^{2}\right) \circ I_{n} \circ \pi_{n}^{X}\right] \delta\left(\phi_{n} \cdot \hat{z}\right) d \mu .
\end{aligned}
$$

where $\varepsilon^{\prime}<\varepsilon<\varepsilon^{\prime \prime}, H_{\varepsilon^{\prime}}^{(n)} \subset H_{\varepsilon}^{(n)} \subset H_{\varepsilon^{\prime \prime}}^{(n)}$. Then $\phi_{n}$. $\hat{z}$ is a vector field on $H^{(n)}$. By the intertwinning formula (6.7)[1], we have

Consider the following formula (cf. [9]):

$$
\begin{equation*}
\int_{0}^{1} f_{\alpha}(s) \dot{b}_{n}^{\alpha}(s) d s=\int_{0}^{1}\left(\frac{1}{\Delta s} \int_{s^{-}}^{s^{+}} f_{\alpha}(t) d t\right) d b^{\alpha}(s)+\sum_{\alpha} \int_{0}^{1}\left(\frac{1}{\Delta s} \int_{s^{-}}^{s^{+}} D_{s, \alpha}^{X} f_{\alpha}(t) d t\right) d s \tag{3.3}
\end{equation*}
$$

where $f(s)$ is a non-adapted $\mathbb{R}^{d}$ valued process with
integral is taken in the sense of Skorohod. some regularity assumptions and the stochastic

Applying this formula to $f_{\alpha}(s)=\phi_{n} \dot{\hat{z}}^{\alpha}\left(s^{-}\right)$,

$$
\begin{aligned}
\delta\left(\phi_{n} \cdot \hat{z}\right)(b)=\sum_{\alpha} & \int_{0}^{1} \phi_{n} \cdot \dot{\hat{z}}^{\alpha}\left(t^{-}\right) \dot{b}_{n}^{\alpha}(t) d t-\int_{0}^{1} D_{t, \alpha}^{X}\left[\phi_{n} \dot{\tilde{z}}^{\alpha}\left(t^{-}\right)\right) d t=\sum_{\alpha} \int_{0}^{1} \phi_{n} \cdot \dot{z}^{\alpha}\left(t^{-}\right) \dot{b}_{n}^{\alpha}(t) d t \\
& \quad-\sum_{\alpha} \int_{0}^{1} \phi_{n} \cdot\left(\int_{t^{-}}^{t^{+}} \frac{t^{+}-s}{t^{+}-t^{-}} \Omega_{\gamma \lambda \beta}^{\alpha}\left(r_{n}(s)\right) \dot{b}_{n}^{\gamma}(s) \bar{z}^{\lambda}(s) \dot{b}_{n}^{\beta}(s) d s\right) \dot{b}_{n}^{\alpha}(t) d t \\
& \quad-\sum_{\alpha} \int_{0}^{1} \phi_{n} \cdot\left(\int_{0}^{t^{-}} \Omega_{\gamma \lambda \beta}^{\alpha}\left(r_{n}(s)\right) \dot{b}_{n}^{\gamma}(s) \bar{z}^{\lambda}(s) d s\right) \cdot \dot{b}_{n}^{\beta}(t) \dot{b}_{n}^{\alpha}(t) d t \\
& \quad-\int_{0}^{1} \phi_{n} D_{t, \alpha}^{X} \dot{\hat{z}}^{\alpha}\left(t^{-}\right) d t-\int_{0}^{1} \dot{\hat{z}}^{\alpha}\left(t^{-}\right) D_{t, \alpha}^{X} \phi_{n} d t
\end{aligned}
$$

where $b_{n}=\pi_{n}^{X}(b)$ and $r_{n}$ is the horizontal lift of $I_{n}\left(b_{n}\right)$ satisfying

$$
d r_{n}(s)=\sum_{\alpha=1}^{d} A_{\alpha}\left(r_{n}\right) \dot{b}_{n}^{\alpha}(s) d s, \quad r_{n}(0)=r_{0}
$$

## Impact Factor:

| ia) | $=6.317$ | SIS (USA) | $=0.912$ | ICV (Poland) | = 6.630 |
| :---: | :---: | :---: | :---: | :---: | :---: |
| ISI (Dubai, UAE | 1.582 | РИНЦ (Rus | = 0.126 | PIF (India) | 1.940 |
| GIF (Australia) | $=0.564$ | ESJI (KZ) | $=9.035$ | IBI (India) | 4.260 |
| IF | $=1.500$ | SJIF (Moroc | $=7.184$ | OAJI (USA) | = 0.35 |

In view of the antisymmetry of $\Omega_{\gamma \lambda \beta}^{\alpha}$ the second and third terms of this expression vanish. By
the construction of $\phi_{n}$, we know that $\varphi_{n} \cdot D_{t, \alpha}^{X} \phi_{n}=$ 0 . Hence

$$
\begin{aligned}
\int_{H_{\varepsilon}^{(n)}(M)} D_{z}^{(n)} & \left(f \cdot \hat{\varphi}_{n}^{2}\right) d v_{n}=\int_{H_{\varepsilon}^{(n)}}\left(f \cdot \hat{\varphi}_{n}^{2}\right) \circ I_{n}(b) \cdot\left[\sum_{\alpha} \int_{0}^{1} \dot{z}^{\alpha}\left(t^{-}\right) \dot{b}_{n}^{\alpha}(t) d t-\int_{0}^{1} D_{t, \alpha^{2}}^{X} \dot{\hat{z}}^{\alpha}\left(t^{-}\right) d t\right] d \mu_{n}(b) \\
& =\int_{H_{\varepsilon}^{(n)}(M)}\left(f \cdot \hat{\varphi}_{n}^{2}\right)(\sigma) \cdot\left[\sum_{\alpha} \int_{0}^{1} \dot{z}^{\alpha}\left(t^{-}\right) d\left[I_{n}^{-1}(\sigma)\right]^{\alpha}(t)-\int_{0}^{1} D_{t, \alpha}^{X} \dot{\hat{z}}^{\alpha}\left(t^{-}\right) d t\right] d v_{n}(\sigma) \\
& =\int_{M_{\varepsilon}^{(n)}} f(\sigma) \cdot\left[\sum_{\alpha} \int_{0}^{1} \dot{z}^{\alpha}\left(t^{-}\right) d\left[I_{n}^{-1}(\sigma)\right]^{\alpha}(t)-\int_{0}^{1} D_{t, \alpha}^{X} \dot{\hat{z}}^{\alpha}\left(t^{-}\right) d t\right] d v_{n, \varepsilon}(\sigma)
\end{aligned}
$$

Finally, we obtain

$$
\int_{M_{\varepsilon}^{(n)}} D_{z}^{(n)} f d v_{n, \varepsilon}=\int_{M_{\varepsilon}^{(n)}} f \delta^{(n)} z d v_{n, \varepsilon}
$$

where $\delta^{(n)} Z$ is given by (6.12)[1].
Theorem (3.3): For any $g \in C_{b}(W(M))$, let $g_{n}$ be the projection of $g$ (see Definition (6.1.17)). Then for any $\mathrm{t}>0$, we have

$$
\tilde{T}_{t}^{(n)} g_{n} \xrightarrow{w} T_{t} g \quad \text { in } L^{2}(W(M), v),
$$

where $T_{t}:=e^{-t L}$.
Proof. Following the notation of the previous

$$
\begin{aligned}
& E^{v_{n, \varepsilon}}\left(T_{t}^{(n)} g_{n} \cdot f_{n}\right)-E^{v}\left(T_{t} g \cdot f\right)=E^{P}\left(g_{n}\left(p_{t}^{n}\right) f_{n}\left(p_{0}^{n}\right)\right)-E^{P}\left(g\left(p_{t}\right) \cdot f\left(p_{0}\right)\right) \\
& \quad=E^{P}\left(\left[g_{n}\left(p_{t}^{n}\right)-g\left(p_{t}^{n}\right)\right] f_{n}\left(p_{0}^{n}\right)\right)+E^{P}\left(g\left(p_{t}^{n}\right)\left[f_{n}\left(p_{0}^{n}\right)-f\left(p_{0}^{n}\right)\right]\right) \\
& \quad+E^{P}\left(g\left(p_{t}^{n}\right)\left[f\left(p_{0}^{n}\right)-f\left(p_{0}\right)\right]\right)+E^{P}\left(\left[g\left(p_{t}^{n}\right)-g\left(p_{t}\right)\right] \cdot f\left(p_{0}\right)\right) .
\end{aligned}
$$

The convergence of the last two terms follows from the a.s. convergence of $p_{t}^{n}$ to $p_{t}$ and the dominated convergence theorem. As for the first, since $v_{n, \varepsilon}$ is the invariant measure of $p_{t}^{n}$, it is estimated by

$$
\begin{aligned}
& C E^{P}\left|g_{n}\left(p_{t}^{n}\right)-g\left(p_{t}^{n}\right)\right|=C E^{v_{n, \varepsilon}}\left|g_{n}\left(\sigma_{v}\right)-g\left(\sigma_{v}\right)\right| \\
& \quad=C E^{\mu}\left(\varphi_{n}^{2}\left|g_{n} \circ I_{n} \circ \pi_{n}^{X}-g \circ I_{n} \circ \pi_{n}^{X}\right|\right) \\
& \quad \leq C E^{\mu}\left(\varphi_{n}^{2}\left|g \circ I-g \circ I_{n} \circ \pi_{n}^{X}\right|\right) \rightarrow 0 .
\end{aligned}
$$

The second is similar.
Proposition (3.4): Under the assumptions of Theorem (6.2.1), the limit in Eq. (6.56) is zero.

Proof. Combining Propositions (6.2.35), (6.2.39), (6.2.40), and Eqs. (6.179) and (6.180) shows
that the limit in Eq. (6.55) vanishes when $\Delta \rightarrow 0$.
Here we collect several inequalities which are straight forward to show, but the frequency of use warrants their mention. For any $a \in \mathbb{R}$ and $p \in \mathbb{N}$,

$$
\begin{align*}
& \left|e^{a}-1\right|^{p} \leq e^{p|a|}-1 \leq p|a| e^{p|a|}  \tag{3.4}\\
& \text { If } a, b>0 \operatorname{and} \alpha \geq 1 \\
& \frac{\sinh (a)}{a} \leq \cosh (a)  \tag{3.5}\\
& \cosh (a) \cosh (b) \leq \cosh (a+b)  \tag{3.6}\\
& \cosh (a)(\cosh (b)-1) \leq \\
& \cosh (a) \cosh (b)-1,  \tag{3.7}\\
& \alpha(\cosh (a) \cosh (b)-1) \leq \\
& \cosh (\alpha a) \cosh (\alpha b)-1 . \tag{3.8}
\end{align*}
$$

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|  | ISRA (India) | $=6.317$ | SIS (USA) | $=0.912$ | ICV (Poland) | $=6.630$ |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| Impact Factor: | ISI (Dubai, UAE) $=\mathbf{1 . 5 8 2}$ | PИHL (Russia) $=\mathbf{0 . 1 2 6}$ | PIF (India) | $=\mathbf{1 . 9 4 0}$ |  |  |
| GIF (Australia) | $=\mathbf{0 . 5 6 4}$ | ESJI (KZ) | $=9.035$ | IBI (India) | $=\mathbf{4 . 2 6 0}$ |  |
|  | $=1.500$ | SJIF (Morocco) $=\mathbf{7 . 1 8 4}$ | OAJI (USA) | $=\mathbf{0 . 3 5 0}$ |  |  |

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