High Gain DC-DC Converter with Enhanced Adaptive MPPT for PV Applications

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ABSTRACT

The increasing demand for electricity has pushed more effort to focus on renewable energy sources to satisfy the consumer. The renewable energy sources are playing a major role in the generation of electricity. Out of all the renewable energy sources, solar has emerged as one of the best sources of energy since it is clean, inexhaustible and eco-friendly. However, the voltage generated by the solar cell is not sufficient for any consumer load and it is also variable. Therefore, it is necessary to implement DC-DC converters for regulating and improving the output voltage of the solar panel. In order to extract the maximum output from the PV (Photovoltaic) panel, a comparative analysis of various MPPT (Maximum Power Point Tracking) algorithms is proposed in this paper. The proposed enhanced adaptive P&O (Perturb and Observe) algorithm is modeled and implemented with a high gain DC-DC converter. The converter investigated in this paper consists of a single power electronic switch (MOSFET) for its operation, which leads to reduction of switching and conduction losses. The proposed converter has less ripple content and a high conversion ratio. A simulation study of the proposed power electronic converter powered by PV source is carried out in MATLAB/SIMULINK and the results are validated using an experimental setup.

Key Words: Enhanced Adaptive Perturb and Observe Algorithm, High Gain DC-DC Converter, Ripple, Photovoltaic.

1. INTRODUCTION

The PV energy generation has become the most predominant form of energy. This is due to the fact, that the energy generated by solar panel can be directly converted into direct current. Furthermore, the solar systems produce clean power, with no pollutant emissions, helping in such a way to strive against the

global warming [1]. The output generated from the PV panel mainly depends upon the junction temperature and the solar insolation level.

The major problem in solar systems is that the operating characteristics of the load and the PV array are

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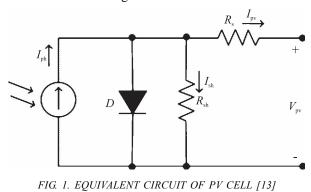
mismatched. To obtain the optimum condition when it is directly connected to the load, a curve between the panel voltage and current is drawn and a point of intersection is determined. MPPT is then employed in the solar system to obtain the maximum power from the PV array and delivers it to the load. Maximum power is transferred to the load by varying the impedance on the load side and also matching it with the peak power at the instant of changing the duty cycle [2]. In this respect, several MPPT techniques are proposed. P&O is the simplest MPPT technique when compared to the conventional types and also exhibits very fast convergence to achieve the MPP (Maximum Power Point). But, the negative side of this method is that, when a perturbation occurs, the algorithm will force the operating point to continuously move in the region of the MPP [3]. Based on the level of perturbation, the power loss gets increased. The next drawback is that the P&O algorithm loses its tracking direction with respect to the irradiance level [4]. When the tracking direction gets deviated, the algorithm becomes mystified and it gets diverged from the MPP [5]. Another major drawback is the tracking of global peak under partial shading condition is poor. To overcome all these problems, an enhanced adaptive technique has been proposed in this paper.

Though maximum power is obtained from the PV panel, the regulation of output voltage is essential since it is variable in nature. Therefore, a power electronic converter has to be interfaced with the solar system. Apart from regulation, the voltage obtained from the PV should match the load side specifications. These issues have triggered a severe demand for the use of high efficient DC-DC converters [6].

To achieve high voltage gain, conventional boost converters with high duty ratio can be used. But, this leads to conduction losses and also results in reverse recovery problems. To overcome these problems, various researchers in the field of power electronic converters have come up with new modified topologies of high gain boost converters. The high gain converters that employ switched capacitors produce high transient current, thus reducing the life of the switched capacitor [7]. This drawback can be eliminated by the integration of voltage doubler circuit along with the switched inductor topology in order to achieve high voltage with reduction of stress across the switches on the power electronic devices [8]. But this scheme requires high number of switching devices, which makes the circuit configuration to be complex and the cost is also high. Therefore, quadratic boost converter is incorporated with the minimum number of switches. This requires transformer with large turns ratio which results in high leakage inductance, more voltage and current spikes on the power switches [9]. To overcome these problems, a single switch high gain boost converter by integrating a transformer-less quadratic boost converter with a conservative model of boost converter is proposed in this paper.

2. PV MODELING AND CHARACTERISTICS

A solar cell is basically a p-n junction which converts the light source into electricity through photovoltaic effect. When exposed to the sunlight, an electron-hole pair is created which is proportional to the incident radiation. A higher range of voltage and current can be attained by incorporating multiple cells [10]. The representation of PV cell is shown in Fig. 1.



The series resistance and the shunt resistance correspond to the internal losses and the leakage current respectively. The output current is a function of solar radiation, temperature and various other parameters.

The PV modeling is done using the following Equations (1-6),

Photo current,
$$I_{ph} = I_{sc} + (ki(T_{op} - T_{ref})^*(I_{rr})$$
 (1)

Reverse Saturation current,
$$I_{rs} = \frac{lsc}{exp\left(\frac{qVOC}{NSKATop}\right)^{-1}}$$
 (2)

Saturation Current,
$$I_s = I_{rs} \left[\frac{T_{op}}{T_{ref}} \right]^3 * exp \left[\left\{ \frac{q * Eg0}{Ak} \right\} \left\{ \frac{1}{T_{ref}} - \frac{1}{T_{op}} \right\} \right]$$
 (3)

Diode Current,
$$I_d = I_s * N_p \left[exp \left\{ \frac{q(Vpv + IpvRs)}{NsAkTop} \right\} - 1 \right]$$
 (4)

Shunt Current,
$$I_{sh} = \frac{(Vpv + IpvRs)}{Rsh}$$
 (5)

Module Output Current, $I_{pv} = (I_{ph} N_p) - I_d - I_{sh}$ (6)

- I_{sc} = short-circuit current in A and K_i= temperature coefficient (0.0017A/K)
- T_{op} and T_{ref} = operating and reference temperatures in K
- $I_{rr} = irradiation on the device surface (W/m²), and$ $the nominal irradiation is 1000W/m². (I_{rr}=I_{rr}/1000)$
- q = Charge of electron (1.6x10-19 C)
- $V_{oc} = Open-circuit voltage (37.8 V)$
- $N_s =$ number of cells connected in series (36)
- K = Boltzmann constant (1.3805x10-23 J/K)
- A =Ideality factor (1.6)
- E_{go} = Band gap energy of the semiconductor (1.1eVfor the polycrystalline Si at 25°C)

3. MPPT ALGORITHM

3.1 Enhanced Adaptive Perturb and Observe Algorithm

The drawbacks of the conventional P&O algorithm can be eliminated with the proposed enhanced adaptive technique. This work ensures the steady state oscillation and decrease in tracking loss deviation. The tracking of global peak power under partial shading is also carried out. Based on the literature survey [11-12], the initial perturbation is set. After that, the algorithm reads the voltage and current values from the PV array. This power is compared with the normalized values during the initial scanning state. When it reaches the maximum power point, it starts oscillating and then five consecutive perturbations are recorded and the oscillations are detected by the enhanced adaptive algorithm [13]. After detecting the oscillation, the perturbation is minimized to the threshold level and the value of 'steady' is set to 1. Now the voltage of the PV is expected to be at MPP since the irradiation level is maintained at a uniform level. After tracking the optimum point, a boundary condition is set on the voltage value at MPP [14-15].

Under partial shading condition, local peaks occur at certain conditions. When the shading level increases gradually with respect to the number of series modules, the local peaks position gets shifted towards right. Therefore, it is necessary to shift the predicted points to the right along with the increasing shading level. The scanning points are set to V_1, V_2, \dots, V_{Ns} . The value of current is determined by choosing the point which is close to the short circuit current and it is used to compute the irradiance level. Then it is shifted to V_2 and the value

of I_2 is noted. In the same manner, the EAPO service the change of irradiance level and shifts the peak points [16]. After scanning all the predicted peak points, the scanned power will be compared. By comparing the obtained values, the global peak point is determined. The EAPO algorithm is demonstrated using a flow chart and is shown in Fig. 2.

4. HIGH GAIN DC-DC BOOST CONVERTER

Normally, classical boost converters are employed for PV applications, but they suffer from severe voltage and current stress when operated at large duty ratios to achieve high gain. Moreover, it produces high ripple both at the input and output side. This can be overcome with the help of a high gain DC-DC converter. Several high gain converter topologies are discussed by various researchers [17-21] and this paper focuses on a topology which combines the conventional boost and quadratic boost to achieve high gain and efficiency. The circuit diagram for the proposed high gain DC-DC converter is shown in Fig. 3.

The operation of the converter is explained in two modes.

Mode-1: Initially, the switch is in ON state and the diodes D_1 and D_4 gets turned-on simultaneously. The current through the capacitors are equal to that of the opposite inductors. The difference in the voltage levels i.e. $(V_{c1} - V_{c3})$ and $(V_{c2} - V_0)$ leads to the turning off of the diodes D_2 and D_5 . Then diode D_3 is reverse based by the voltage $(-V_{c2})$.

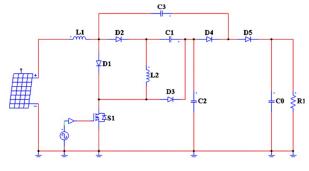


FIG. 3. HIGH GAIN DC-DC CONVERTER

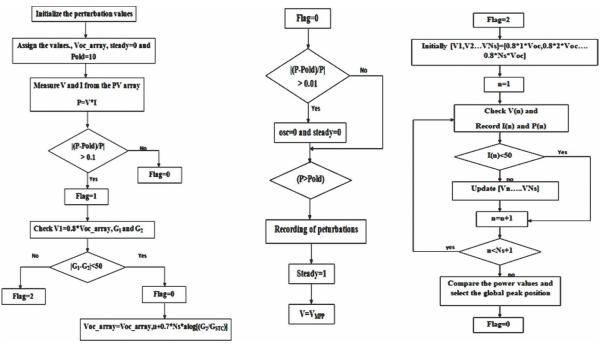


FIG. 2. FLOWCHART FOR ENHANCED ADAPTIVE P&O ALGORITHM

The value of the voltage in inductor L_1 is nothing but the input voltage V_g , and the voltage in inductor L_2 is equal to the difference of the capacitor voltages C_1 and C_2 . The value of current in capacitors C_1 and C_2 is equal to that of the current flowing through inductor L_2 and L_1 respectively. At this condition the charging of capacitor C_2 takes place.

Mode-2: In this mode, the diodes D_2 , D_3 and D_5 get turnedon at the time when the switch is in OFF state. Now the voltage across capacitors becomes equal and the current through the inductors starts decreasing linearly. The voltage across the capacitor C_1 makes the diode D_1 to become reverse bias and the negative voltage $(V_{c2} - V_{c0})$ across the capacitors C_2 and C_3 makes the diode D_4 to be turned off. The decrease in inductor currents i_{L1} and i_{L2} is proportional to the voltage $(V_g + V_{c3} - V_0)$ and $(-V_{c1})$. Capacitor C_2 and C_3 are being charged by the currents across inductor L_1 . The converter is designed using the following equations,

The value of inductor,
$$I_1 = \frac{D.Vin}{2fs\Delta IL1}$$
 (7)

The value of inductor,
$$I_2 = \frac{D.Vin}{2fs\Delta IL2}$$
 (8)

where, D is the duty ratio, V_{in} is the input voltage, f_s is the switching frequency, I_{L1} is the current through inductor L_1 , I_{L2} is the current through inductor L_2

The current across the inductor L_1 is,

$$I_{L1} = \frac{I_{o}}{(1-D)^{2}}$$
(9)

where, I₀ is the output current

The current across the inductor L_2 is,

$$I_{L2} = \frac{I_o}{1 - D} \tag{10}$$

The voltage across the inductor is,

$$V_{L1} = V_{in} \tag{11}$$

where, V_{in} is the input voltage

The voltage across the inductor is

$$V_{L2} = V_{c1} - V_{c2}$$
(12)

Where, V_{c1} and V_{c2} are the voltages across capacitors C_1 and C_2 , respectively.

The value of the capacitor C_1 is,

$$C_1 = \frac{I_{oD}}{(1-D)\Delta Vc1 fs}$$
(13)

The value of the capacitor C_2 and C_3 is,

$$=\frac{I_{oD}}{\Delta Vc2fs}$$
(14)

Where,

$$C_2 = \frac{VS}{1 - D}$$
(15)

The voltage across the capacitors are,

$$V_{c2} = V_{c3}$$
 (16)

 $V_{c1} = 2V_{c2} - V_{o}$ $\tag{17}$

 $V_{c2} = [1/(2-D)] V_{o}$ (18)

$$V_{in} = D'(V_o - V_{c3})$$
 (19)

Where, D' = (1-D), D is the duty ratio, V_{in} is the input voltage, V_{o} is the output voltage.

The voltage gain for the converter is given by,

Voltage gain,
$$M = (V_o/V_{in}) = \frac{2-D}{(1-D)^2}$$
 (20)

Using the above equations, the simulation parameters are designed for the high gain converter and it is shown in Table 1.

5. SIMULATION RESULTS

The PV modelling is done using MATLAB/SIMULINK and the results are shown in Fig. 4. The model has been designed for 250W, the PV and IV characteristics for the panel is shown in Figs. 5-6 respectively. From Fig. 5, it is clear that the maximum power occurs at a value which is nearer to 250W with respect to that of the open circuit voltage.

Fig.6., shows the waveform for short circuit current with respect to that of the open circuit voltage. The curve indicates that the rated value of current is obtained.

The dynamic power waveforms for the MPPT algorithms are shown in Fig. 7.

Parameters	Range
Input Voltage, Vin	37.8 V
Inductance, L1	5mH
Inductance, L2	25µН
Capacitance,C1	50µF
Capacitance, C2 and C3	100µF
Output Capacitance, C0	1000µF
Resistance, R1	250?
Duty ratio	0.4
Switching Frequency, fs	90kHz

TABLE 1. SPECIFICATION OF HIGH GAIN BOOST CONVERTER

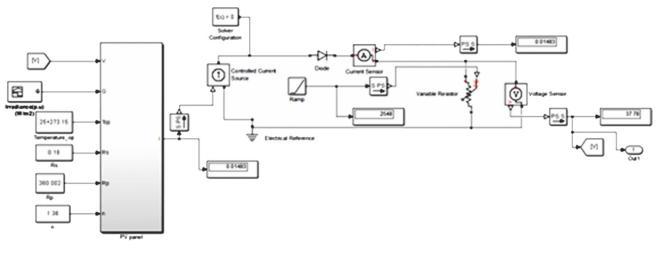


FIG. 4. SIMULINK MODEL FOR PV PANEL

Fig. 7, shows the dynamic power waveform for the proposed MPPT algorithm along with the basic perturb and observe and adaptive perturb and observe algorithm. The proposed enhanced adaptive P&O algorithm is compared with the other conventional P&O algorithms based on tracking efficiency and the results are tabulated in Table 2.

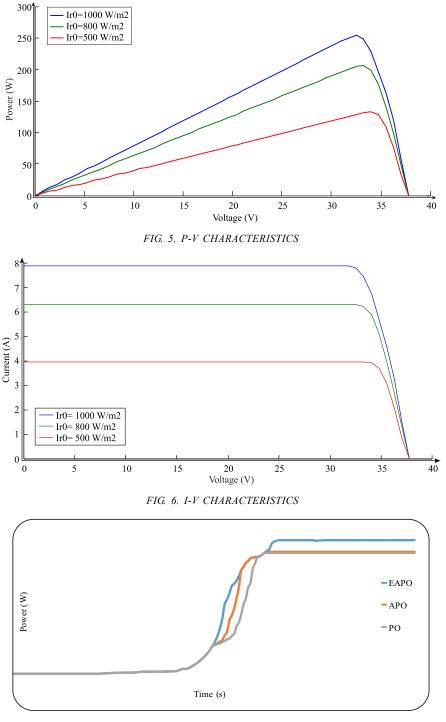


FIG. 7. POWER WAVEFORM FOR MPPT ALGORITHMS

Mehran University Research Journal of Engineering & Technology, Volume 38, No. 3, July, 2019 [p-ISSN: 0254-7821, e-ISSN: 2413-7219] 547

From Table 2, it is found that the proposed MPPT algorithm is very efficient when compared to the other MPPT techniques. The tracking efficiency is 95.62%

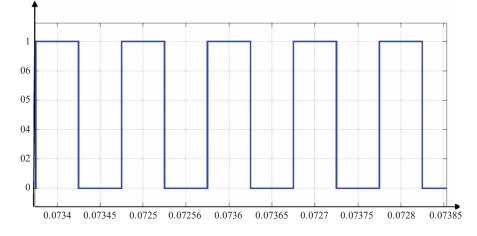
Fig. 8 shows the generated gate pulses after the implementation of enhanced adaptive MPPT algorithm.

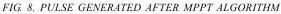
Algorithms	Tracking Efficiency (%)
Peturb & Observe	88.65
Adaptive Peturb & Observe	90.63
Enhanced Adaptive Peturb & Observe	95.62

The simulation of high gain DC-DC converter is carried out using MATLAB/SIMULINK for an input voltage of 37.8V. The Simulink model is shown in Fig. 9.

The waveforms for voltage, current and power are shown in Figs. 10-12 respectively.

Fig. 10 shows the waveform for output voltage of the high gain converter. The output voltage is in the range of 146.3V and the ripple is also low. The output voltage ripple waveform is shown in Fig. 11.





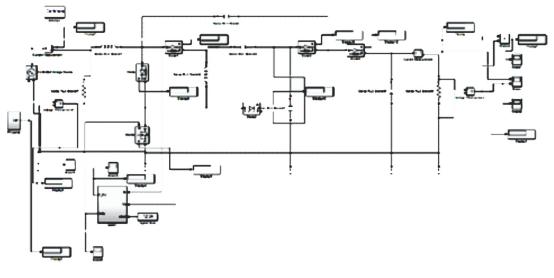
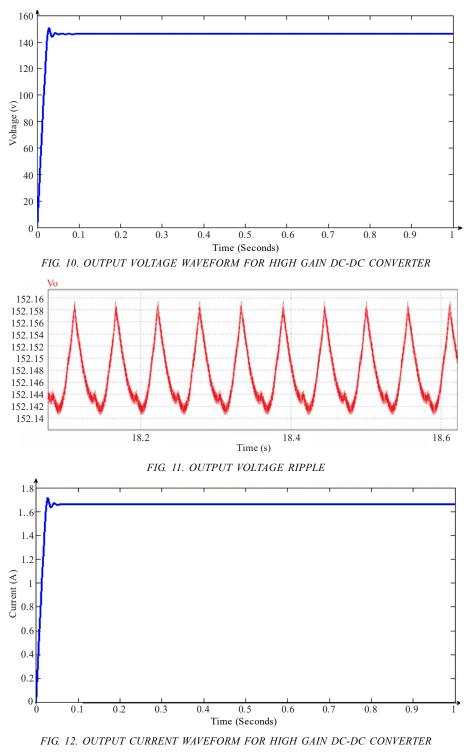


FIG. 9. MATLAB/SIMULINK MODEL FOR HIGH GAIN DC-DC CONVERTER

From Fig. 11, it is found that the output voltage ripple is in the range of 0.018V which is a low ripple value.

Fig. 12 shows the waveform for the output current. The current is maintained at 1.656A with less ripple content. The waveform is shown in Fig. 13.



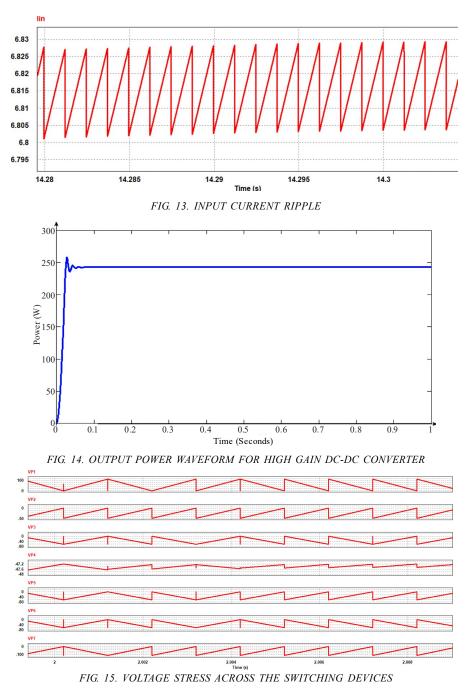
Mehran University Research Journal of Engineering & Technology, Volume 38, No. 3, July, 2019 [p-ISSN: 0254-7821, e-ISSN: 2413-7219] 549

From Fig. 13, it is clearly indicated that the input current ripple is in the range of 0.03A which is a low ripple value.

From Fig. 14, it is found that the maximum power has been achieved. It is in the range of 242.2 W and the required power rating is 250W.

The voltage stress across the main devices for the proposed topology is shown in Fig. 15.

Fig.15., shows the waveform for voltage stress across the MOSFET switch and the conducting diodes for the proposed topology. From Fig. 15, it is clear that the voltage stress is at nominal level.



Mehran University Research Journal of Engineering & Technology, Volume 38, No. 3, July, 2019 [p-ISSN: 0254-7821, e-ISSN: 2413-7219] 550

A graph drawn between the percentage of efficiency with respect to the load for the high gain converter topology is shown in Fig. 16.

From Fig. 16, it is clear that the proposed converter gives an efficiency of 95.6% at full load.

The high gain converter investigated in this paper is compared with some other topologies of boost converter based on the parameters such as output voltage ripple, input current ripple, duty ratio, voltage gain and voltage and current stress across the main switch. The comparison of parameters is shown in Table 3.

From Table 3, it is clear that the proposed high gain converter is efficient in terms of ripple voltage, ripple current, duty ratio and voltage gain when compared to the other boost converter topologies.

The high gain topologies are also compared based on the number of devices used, control complexity and filter components. The comparison is shown in Table 4.

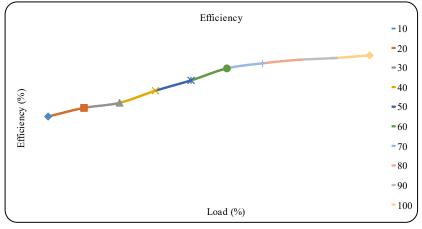


FIG. 16. EFFICIENCY CURVE

TABLE 3. COMPARISON OF PARAMETERS

Parameters	Cascaded Boost with Single Switch	New Cascaded Boost with Reduced Losses	Single Switch Inductor Capacitor Topology	Quadratic DC-DC with Coupled Inductor	Proposed High Gain DC- DC Converter
Output Voltage Ripple (V)	0.1	0.5	0.2	0.04	0.018
Input Current Ripple (A)	0.3	0.78	0.1	0.1	0.03
Duty Ratio	0.4	0.4	0.4	0.4	0.4
Voltage Gain	1.67	2.78	2.02	2.66	4.45

Descriptions	Cascaded Boost with Single Switch	New Cascaded Boost with Reduced Losses	Single Switch Inductor Capacitor Topology	Quadratic DC-DC with Coupled Inductor	Proposed High Gain DC-DC Converter
No. of Main Switches	1	2	1	4	1
No. of Diodes	3	2	3	0	4
Noof Inductors	4	4	5	5	6
Control Complexity	Difficult	Complex control circuit	Complex	Need Individual circuit	It can be implemented by simply obtaining a critical point

TABLE 4. COMPARISON OF TOPOLOGIES

From Table 4, it is clear that the proposed high gain converter is best in terms of reduced number of main switching devices and also in controlling aspects.

The voltage and current stress values for the converter topologies are tabulated in Table 5.

The waveforms for the ripple values and voltage gain with respect to the duty ratios are shown in Figs.17-19 respectively.

Fig. 17, shows the variation in input current ripple by varying the duty ratio for some of the high gain converter topologies discussed in the literature. It is clear that the high gain DC-DC converter investigated in this paper has very low current ripple compared to the other topologies. It is in the range of 0.03A.

Fig. 18, shows the variation in output voltage ripple by varying the duty ratio. It is clear that the high gain DC-DC converter investigated in this paper has very low voltage ripple compared to the other topologies. It is in the range of 0.018 V

The variation of voltage gain with respect to the duty ratio is shown in Fig. 19, and it is found that high conversion gain can be achieved even at low duty ratio. For the required power rating, high voltage conversion has been achieved at a duty ratio of 0.4

The full load efficiency for all the discussed topologies is shown in Table 6.

From table 6, it is clear that the proposed topology is highly efficient compared to the other topologies.

TABLE 5. VOLTAGE AND CURRENT STRESS CALCULATION

Topologies	Voltage Stress (V)	Current Stress (A)
Cascaded boost with single switch	45.29	4.3
New cascaded boost with reduced losses	75.75	3.2
Single switch inductor capacitor topology	21.7	5.4
Quadratic DC-DC with coupled inductor	69.12	3.1

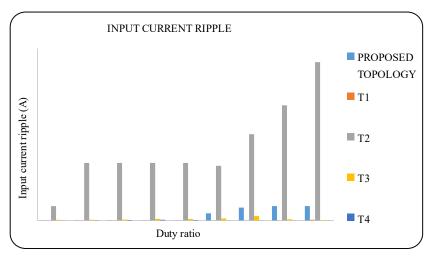


FIG. 17. WAVEFORM FOR INPUT CURRENT RIPPLE

TABLE 6. EFFICIENCY FOR CONVERTER TOPOLOGIES

Topologies	Efficiency (%)
Cascaded boost with single switch	91.2
New cascaded boost with reduced losses	92.5
Single switch inductor capacitor topology	77
Quadratic DC-DC with coupled inductor	88
High gain DC-DC converter	95.6

6. HARDWARE IMPLEMENTATION

To verify the theoretical results and to measure the performance of the system, the proposed converter topology is simulated and validated with an experimental setup for the following speciûcations: $V_{in} = 18.3 \text{ V}$, $V_o = 84 \text{ V}$ and $f_s = 90 \text{ kHz}$. The inductors values are 5 mH, 25 μ H for L_1 and L_2 respectively. The value of the capacitor is 50 μ F for C_1 and 100 μ F for C_2 and C_3 . The output capacitor

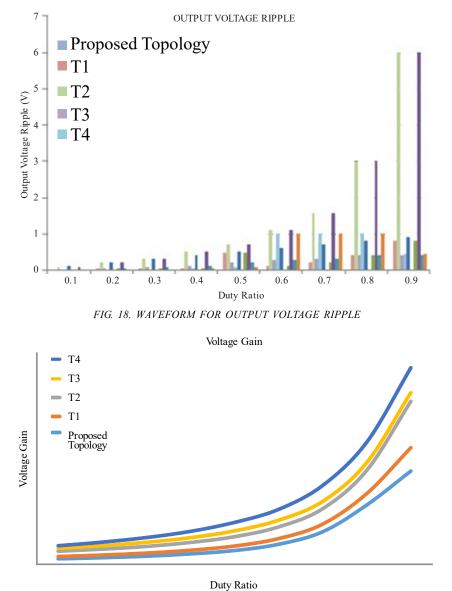


FIG. 19. WAVEFORM FOR VOLTAGE GAIN AT DIFFERENT DUTY RATIOS

 (C_{o}) is set to 1000 μ F. The hardware setup of the high gain converter is shown in Fig. 20.

Power MOSFETs are chosen as the semiconductor switch for the proposed converter and gating pulses are generated using the hardware implementation of the converter is shown in Fig. 20. The input voltage of 18.3 V is given and the voltage is boosted up to 4.45 times which is equal to the simulated results. The obtained output voltage is 84 V.

Fig. 21, shows the gating pulse for the converter circuit. The pulse pattern is programmed using arduino UNO 3 board for a duty ratio of 0.4

Fig. 22, shows the experimental results for the high gain converter. It is clear that output voltage is in the range of 84V.

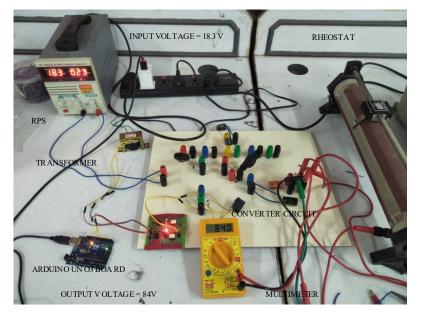


FIG. 20. EXPERIMENTAL SETUP

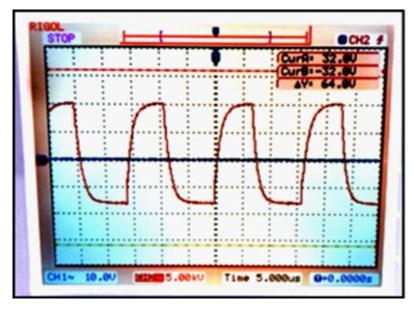
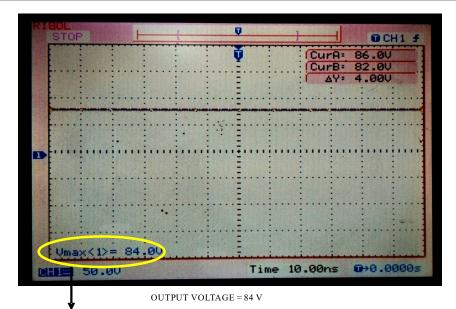


FIG. 21. GATE PULSE FOR CONVERTER

Mehran University Research Journal of Engineering & Technology, Volume 38, No. 3, July, 2019 [p-ISSN: 0254-7821, e-ISSN: 2413-7219] 554



High Gain DC-DC Converter with Enhanced Adaptive MPPT for PV Applications



7. CONCLUSION

An enhanced adaptive P&O technique is implemented to obtain the maximum power from the solar panel and the PV acts as an input source for the converter configuration. The proposed MPPT algorithm is compared with the basic P&O algorithm and also with an adaptive technique and it is proved to have a very good tracking efficiency of 95.62%. The high gain converter is implemented with the proposed enhanced MPPT technique and results in high voltage gain with less voltage ripple compared to the other conventional topologies discussed. The simulation results are validated using an experimental setup. Hence, the proposed converter topology with high voltage gain ratio is suitable for PV applications.

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High Gain DC-DC Converter with Enhanced Adaptive MPPT for PV Applications

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