MODIFIED ARMIJO RULE ON GRADIENT DESCENT AND CONJUGATE GRADIENT

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ABSTRACT

Armijo rule is an inexact line search method to determine step size α_k in some descent method to solve unconstrained local optimization. Modified Armijo was introduced to increase the numerical performance of several descent algorithms that applying this method. The basic difference of Armijo and its modified are in existence of parameter $\mu \in [0,2)$ and estimating parameter L_k that be updated in every iteration. This article is comparing numerical solution and time of computation of gradient descent and conjugate gradient hybrid Gilbert-Nocedal (CGHGN) that applying modified Armijo rule. From program implementation in Matlab 6, its known that gradient descent was applying modified Armijo more effectively than CGHGN from one side: iteration needed to reach some norm of gradient $||g_k||$ (input by the user). The amount of iteration was representing how long the step size of each algorithm in each iteration. In another side, time of computation has the same conclusion.

Keywords: Armijo line search; conjugate gradient hybrid Gilbert-Nocedal; gradient descent; modified Armijo line search

1. INTRODUCTION

Optimization is still an interesting issue to be learned and developed, especially numerical methods for finding solutions. This is known as numerical optimization. Optimization is the process of finding the optimal solution of a problem either with constraints or without constraints. Numerical optimization allows the discovery of solutions to problems that are difficult to be solved analytically.

The optimization problem is essentially a matter of minimizing a function f(x). As for maximization, a function f(x) can also be formed as a minimization problem of function -f(x). To solve the minimization problem, some descent iterative methods have been introduced, including gradient descent (steepest descent) and conjugate gradient methods. These two methods are just some of the many methods that can be used to solve local optimization problems. There is much useful application of gradient descent method. One of them is to find the saddle point of a complex integral (Wang, 2008). While Chen (2009) use gradient descent to fit the measured data of laser

grain-size distribution of the sediments.

While in the conjugate gradient method itself there are various types of parameter determination β_k . In this paper, we will use conjugate gradient hybrid Gilbert-Nocedal which is a hybrid of Fletcher-Reeves conjugate gradient (FR) and Polak-Ribiere-Polyak conjugate gradient (PRP).

Gradient descent and conjugate gradient algorithms start with determining the initial point to run the first iteration. The next points will be obtained from each iteration in which the conditions determined will converge to the optimum solution of the optimization objective function. One important part of these two algorithms is the determination of step size (α_k) on each iteration. This step size determination can be done in many ways called line search. One of the line search rules often used is Armijo rule.

To improve the numerical performance of Armijo rules, Shi (2005) have introduced and developed Armijo modification rules. The difference with classical Armijo is the value of parameter $\mu \in [0,2)$ and L_k which is updated on each iteration with a certain estimate. In modified

Armijo rules, it is easier to obtain larger step sizes, meaning that with the same stopping criteria, the iterations required by a descent algorithm will be less than using classical Armijo. This will be compared to the gradient descent and conjugate gradient hybrid Gilbert-Nocedal algorithms. Likewise, the time required for each algorithm to solve the optimization problem by applying the classical Armijo rules and its modification in step size determination.

2. METHODS

2.1. Gradient Descent

Gradient descent is one of the optimization algorithms for the problem of unconstrained minimization. The problem is to minimize $f: I \to \mathbb{R}, I \subset \mathbb{R}^n$. The iteration renews x_k so that in the end of iterations, there is an approximation of the above minimization problem. To find the local minimum of a function using gradient descent, one of the important steps is to determine the descent direction, d_k , as the negative of the gradient $g_k = \nabla f(x)$ of the objective function f(x) at k^{th} iteration point. Next, select the step size α_k by using line search, either in exact or inexact.

For more details about this method, the following is gradient descent algorithm.

Step 0. Given starting point x_0 , k = 0.

Step 1. Select the descent direction $d_k = -g_k$. If $d_k = 0$, then the iteration stops.

Step 2. Select step size α_k using line search method (either exact or not exact).

Step 3. Renew the point $x_{k+1} = x_k + \alpha_k d_k$, k = k + 1. Return to step 1.

The iteration stops if the iteration termination criterion has been reached. for example if the k -th point is close enough to the minimum point of the destination function.

2.2. Conjugate Gradient

Suppose that a quadratic function optimization problem will be solved as follows.

$$Min f(x) = \frac{1}{2}x^T Q x + q^T x$$

The descent direction, d_k , of the conjugate gradient is Qconjugate vectors, where Q is the positive definite matrix found in the function f(x) above.

Suppose given a starting point x_0 . The descent direction for the starting point x_0 uses the descent direction of the descent gradient algorithm i.e

 $d_0 = -g_0 = -\nabla f(x_0).$

In this paper, the descent direction, d_k , is determined as follows:

$$d_k = \begin{cases} -g_k, & k = 0\\ -g_k + \beta_k d_{k-1}, & k \ge 1 \end{cases}$$

Where $g_k = \nabla f(x_k)$ and β_k are parameters. Actually, there are several types of conjugate gradient algorithm based on an estimation of parameter β_k . Some of them by Andrei (2007) are as follows:

• Fletcher-Reeves (FR) conjugate gradient

$$\beta_k^{FR} = \frac{g_k^T g_k}{g_{k-1}^T g_{k-1}}$$

• Poly-Ribiere-Polyak (PRP) conjugate gradient

$$\mathcal{B}_{k}^{PRP} = rac{g_{k}^{T} y_{k}}{g_{k-1}^{T} g_{k-1}}, y_{k} = g_{k} - g_{k-1}$$

• Dai-Yuan (DY) conjugate gradient $a_{k}^{T} a_{k}$

$$\beta_{k}^{DY} = \frac{g_{k}g_{k}}{y_{k}^{T}s_{k}}, y_{k} = g_{k} - g_{k-1},$$
$$s_{k} = x_{k} - x_{k-1}$$

• Hestenes-Stiefel (HS) conjugate gradient T_{rr}^{T}

$$\beta_{k}^{HS} = \frac{g_{k}^{T} y_{k}}{y_{k}^{T} s_{k}}, y_{k} = g_{k} - g_{k-1}, \\ s_{k} = x_{k} - x_{k-1}$$

• Conjugate descent (CD)

$$\beta_k^{CD} = -\frac{g_k^T g_k}{g_{k-1} s_k}, s_k = x_k - x_{k-1}$$

• Liu-Storey (LS) conjugate gradient

$$\beta_k^{LS} = -\frac{g_k^T y_k}{g_{k-1} s_k}, s_k = x_k - x_{k-1}$$

In addition to several types of determination of the parameters of β_k mentioned above, there are also some hybrids of the types that have been developed. But in this paper will be used conjugate gradient hybrid Gilbert-Nocedal as follows.

$$\beta_{k}^{GN} = \begin{cases} -\beta_{k}^{FR} & \text{if } \beta_{k}^{PRP} < -\beta_{k}^{FR}, \\ \beta_{k}^{PRP} & \text{if } |\beta_{k}^{PRP}| \leq \beta_{k}^{FR}, \\ \beta_{k}^{FR} & \text{if } \beta_{k}^{PRP} > \beta_{k}^{FR}. \end{cases}$$

It can be written briefly,

$$\beta_k^{GN} = max \left\{ -\beta_k^{FR}, min\{\beta_k^{PRP}, \beta_k^{FR}\} \right\}.$$

For more details about this method, here is the conjugate gradient algorithm.

Step 0. Given starting point x_0 , k_0 .

Step 1. For $k = 0, d_k = -g_k$. For $k \ge 1$, find β_k , $d_k = -g_k + \beta_k d_{k-1}$. If $d_k = 0$, then the iteration stops.

Step 2. Select step size α_k using line search method (either exact or not exact).

Step 3. Renew the point $x_{k+1} = x_k + \alpha_k d_k, k =$

k + 1. Return to step 1.

2.3. Line Search Method

To determine the step size, α_k , there are many line search methods that can be used, either in exact or inexact. One method of line search that is not exact is the rule of Armijo.

2.3.1. Line Search Armijo

The Armijo rules in determining step size are as follows:

$$\alpha_{k} = \max\{s_{k}, \beta s_{k}, \beta^{2} s_{k}, ...\}$$

That fulfills
$$f(x_{k} + \alpha d_{k}) - f_{k} \leq \sigma \alpha g_{k}^{T} d_{k}$$

Where
$$s_{k} = -\frac{g_{k}^{T} d_{k}}{L \|d_{k}\|^{2}}, \beta \in (0,1), \sigma \in \left(0, \frac{1}{2}\right), L > 0$$

2.3.2. Modified Armijo

In this modified Armijo rule, it will be found that the step size, α_k , which is defined as greater than that defined in the classic Armijo rules. In other words, the step size defined on the modified Armijo rule is easier to find than the step size in the classic Armijo rules.

The modified Armijo Rules by Shi (2005) are as follows:

Determine the scalars s_k , β , L_k , μ , and σ , where

$$s_{k} = -\frac{g_{k}^{T}d_{k}}{L_{k}\|d_{k}\|^{2}},$$

$$\beta \in (0,1), L_{k} > 0, \mu \in [0,2), \sigma \in \left(0, \frac{1}{2}\right),$$

and α_k is the largest α scalar in $\{s_k, \beta s_k, \beta^2 s_k, ..., \}$ such that

$$f(x_k + \alpha d_k) - f_k \le \sigma \alpha \left[g_k^T d_k + \frac{1}{2} \alpha \mu L_k \| d_k \|^2 \right]$$

2.3.3. *L_k* Estimation

In the modified Armijo rule there is a parameter that needs to be estimated and updated on each iteration, ie L_k . Here is the difference between the classic Armijo rules and it's modified, as well as the μ parameter. In the classic Armijo rule, the parameter L is not updated on each iteration. L_k in the modified Armijo rule can be approximated by the Lipschitz constant of the gradient g(x) of the objective function f(x), M'. If M' is given, then, of course, can be taken $L_k = M'$. However, M' is often unknown in many cases, so the L_k parameter can be estimated in one of the following ways.

Let $\delta_{k-1} = x_k - x_{k-1}$, $y_{k-1} = g_k - g_{k-1}$, k = 2,3,4,... Then the parameter value L_k can be determined as follows.

$$L_{k} = \max\left\{\frac{\|y_{k-i}\|}{\|\delta_{k-i}\|} \middle| i = 1, 2, ..., M\right\}$$

 $L_k = \frac{\|y_{k-1}\|}{\|\delta_{k-1}\|}$

Where $k \ge M + 1$, M is a positive integer. The second way to estimate these parameters is as follows.

$$L_k = \frac{\delta_{k-1}^{l} y_{k-1}}{\|\delta_{k-1}\|^2}$$

$$L_{k} = \max\left\{\frac{\delta_{k-i}^{T} y_{k-i}}{\|\delta_{k-i}\|^{2}} \middle| i = 1, 2, \dots, M\right\}$$

The third way is as follows. $L_k = \frac{\|y_{k-1}\|^2}{\delta_{k-1}^T y_{k-1}}$

or

or

$$L_{k} = \max\left\{\frac{\|y_{k-i}\|^{2}}{\delta_{k-i}^{T}y_{k-i}}\right| i = 1, 2, ..., M\right\}$$

As for k = 1 taken $L_1 = 1$.

The above estimates are just a few of the many ways to estimate M'. The above estimates will be used in the gradient descent and conjugate gradient hybrid Gilbert-Nocedal (CGHGN) algorithms which contain modifications to Armijo's rules in it (Shi, 2005).

3. RESULTS AND DISCUSSION

3.1. Numerical Results for Test Function with Gradient Descent

The gradient descent algorithm with modified Armijo rules, as described in the above sections, is applied to Matlab 6 software, with an estimated parameter L_k , various scalar inputs β, σ, μ maximum iteration, and maximum errors ε .

The numerical results of two variable test functions using gradient descent algorithm with estimated parameter $L_k = \frac{||g_k - g_{k-1}||}{||x_k - x_{k-1}||}$, the parameter value is selected $\beta = 0.87$, $\sigma = 0.38$, Maximum iteration 100, and the maximum difference between analytical solutions and numerical solutions $\varepsilon = 0.005$, listed in Table 1 below. Iteration will stop if either one of the maximum iterations or the maximum difference between the analytical solution and the numerical solution is reached. In each of the following tables, compare the numerical solution of the test function with the parameter value range μ at [0,2).

From Table 1 below it can be seen that in a simple function, with $\mu > 0$, there are fewer

iterations and $||g_k||$ is much smaller. $\mu = 0$ represents the classical Armijo rule with L = 1, not updated on each iteration, whereas $\mu > 0$ represents the modified Armijo rule with L_k updated on each iteration. While on the Quadric function, the gradient descent with modified Armijo works better than the classic Armijo. This is demonstrated by the achievement of $||g_k||$ which is not much different, modified Armijo requires much less iteration. In the Zakharof function, of the number of iterations, the classical Armijo seems to work a little better than the modification. However, the $\|g_k\|$ obtained by Armijo modification is slightly smaller than the classic Armijo. Almost the same in Himmenblau function, on some values μ , modified Armijo works a little better, but on some other μ values, on the contrary, it works a little worse than the classic Armijo.

Table 1. Numerical Results of Two Variable TestFunctions with Gradient Descent

	Number of		
μ	iteration	Ε	$\ g_k\ $
	(<i>k</i>)		
	Quadric f	unction with x_0	(1,2)
0	20	5.961 (10 ⁻⁶)	0.0043994
0.5	4	2.3624 (10 ⁻⁶)	0.0045728
1.0	4	1.2997 (10 ⁻⁵)	0.0048104
1.5	4	1.2997 (10 ⁻⁵)	0.0048104
1.99	4	1.2997 (10 ⁻⁵)	0.0048104
	Zakharof	function with x_0	(1,2)
0	4	7.381 (10 ⁻⁸)	0.00081505
0.5	6	$5.181(10^{-9})$	0.00021548
1.0	6	$5.181(10^{-9})$	0.00021548
1.5	6	$5.181(10^{-9})$	0.00021548
1.99	6	5.181(10 ⁻⁹)	0.00021548
	De Jong	function with x_0 (1,2)
0	4	1.0207 (10 ⁻⁶)	0.0020206
0.5	2	9.9104 (10 ⁻²⁹)	1.991 (10 ⁻¹⁴)
1.0	2	$2.4155(10^{-28})$	$3.1048(10^{-14})$
1.5	2	$2.4155(10^{-28})$	$3.1048(10^{-14})$
1.99	2	$2.4755(10^{-28})$	$3.1468(10^{-14})$
	Himmenbla	u function with x	0 (0,0)
0	14	1.9501 (10 ⁻⁷)	0.0033515
0.5	12	$2.0832(10^{-8})$	0.0015424
1.0	12	1.6794 (10 ⁻⁷)	0.0032052
1.5	10	3.8923 (10 ⁻⁸)	0.0014833
1.99	17	2.5695 (10-7)	0.0039309
McCormic function with x_0 (0,0)			
0	8	1.9132	0.0020333
0.5	7	1.9132	0.0020157
1.0	7	1.9132	0.0023628
1.5	5	1.9132	0.0048835
1.99	5	1.9132	0.0016221

With a bit more iteration but $||g_k||$ which is also slightly smaller, in Zakharof and Himmenblau functions, it cannot be concluded that gradient descent with Armijo modification is not better than gradient descent with classic Armijo, although it cannot be concluded otherwise. Moreover, it turns out the numerical results of the De Jong function show again that modified Armijo is still better than classic Armijo.

Figures 1.a and 1.b below show the different results of the gradient descent iteration using classic Armijo with those using modified Armijo. From the figure, it can be seen that the modified Armijo requires fewer iterations to satisfy the termination criteria ($\varepsilon < 0.005$). In other words, modified Armijo converges faster on the minimum solution of the optimization problem.



Figure 1.a Gradient Descent with Classic Armijo ($\mu = 0$) on Quadric Function



Figure 1.b Gradient Descent with Modified Armijo on Quadric Function

While Figure 2.a and 2.b show differences in the effect of parameter values μ . With larger μ , the step size will be larger.



Figure 2.a Gradient Descent with Modified Armijo on DeJong Function ($\mu = 1, \mu = 1.5$)



Figure 2.b Gradient Descent with Modified Armijo on DeJong Function ($\mu = 1.99$)

To summarize in general this comparison, then there should be test functions with larger dimensions to test the method. The parameters used are the same as the parameters used in the two-dimensional test function in Table 1. But the termination criterion used is different, ie if it has reached maximum iteration 1000 iterations or $||g_k|| < 0.005$. The numerical results of gradient descent with classical Armijo rules and its modified on large-dimensional test functions are presented in Table 2 and Table 3.

Using a four-dimensional test function, it can be seen that gradient descent with modified Armijo works better in terms of a number of iterations required to achieve the same $||g_k||$ than the classical Armijo that is < 0.005. In each of the four-dimensional functions in Table 2, modified Armijo always works better than the classical Armijo, even though the termination requirement ($\varepsilon < 0.005$) is same, the modified Armijo still gets a smaller $||g_k||$ than the classic Armijo, with much less number of iterations. In Powell Singular function, if the iteration is not limited to 1000 iterations, then to get the expected $||g_k||$, the process has not been completed. That means the required iteration will be much more than the modified Armijo. In Powell Singular, Watson, Trigonometric, and Penalty II functions, it is also generated that the iterations needed will be less as the parameter value of μ is greater. This proves that selection of this parameter value has important value in modified Armijo.

Similarly, for the 8 dimension test function, the results can be seen in Table 3. At Watson function, it is seen that there is a significant decrease in the number of iterations of the classical Armijo application to the application of its modification. While in Penalty II, there was also a decrease in the number of iterations although not as significant in the Watson function. This further reinforces the assumption of early test functions that modified Armijo works better than classical Armijo on the gradient descent algorithm.

Table 2. The Numerical Result of 4 DimensionTest Function with Gradient Descent

.,	Number of	F	lla ll	
μ	iteration(k)	Ľ	II 9 k II	
4 dimension Powell Singular function with x_0 (1,1,1,1)				
0	1000	0.00040193	0.013225	
0.5	279	0.00020607	0.0049055	
1.0	209	0.00020451	0.0049746	
1.5	182	0.00020795	0.0049696	
1.99	169	0.00020783	0.0049937	
4	dimension Wat	son function with	$x_0(0,0,0,0)$	
0	410	0.0060494	0.0047514	
0.5	129	0.0060433	0.0042924	
1.0	100	0.0060441	0.0044026	
1.5	96	0.0060496	0.0047381	
1.99	83	0.0060247	0.0039382	
4	dimension Pena	alty function with	$x_0(1,2,3,4)$	
0	84	0.0062071	0.004998	
0.5	2	0.0017474	0.001944	
1.0	2	0.0017474	0.001944	
1.5	2	0.0017474	0.001944	
1.99	2	0.0017474	0.001944	
4 dir	nension Variab	ly-Dimensioned f	function with x_0	
		(0,0,0,0)		
0	98	2.6045 (10 ⁻⁶)	0.0049899	
0.5	17	1.2441 (10-9)	0.00039367	
1.0	17	1.2441 (10-9)	0.00039367	
1.5	17	1.2441 (10-9)	0.00039367	
1.99	17	1.2441 (10 ⁻⁹)	0.00039367	
	4 dimension Tri	gonometric funct	ion with x_0	
	(0.2	5,0.25,0.25,0.25)		
0	18	0.00035521	0.0039039	
0.5	12	0.00033347	0.0036763	
1.0	10	0.00040127	0.0046417	
1.5	10	0.00039599	0.004532	
1.99	10	0.00038882	0.0044509	
4 0	limension Pena	lty II function wit	$h x_0 (1,1,1,1)$	
0	16	0.82485	0.0046897	
0.5	13	0.82485	0.0035263	
1.0	12	0.82485	0.002263	
1.5	12	0.82485	0.002263	
1.99	12	0.82485	0.002263	

μ	Number of iteration (k)	Ε	$\ g_k\ $			
8 dim	ension Watson fu	unction with x_0	(0,0,0,0,0,0,0,0),			
m	aximum number	of iterations:10	$00, \varepsilon < 0.05$			
0	249	0.0056431	0.049389			
0.5	87	0.0060244	0.049453			
1.0	55	0.0060305	0.048821			
1.5	56	0.005936	0.047586			
1.99	48	0.0061168	0.048974			
	8 dimension Penalty II function with x_0					
(1,1,1	,1,2,2,2,2), maxim	mum number of	iterations:1000,			
	$\varepsilon < 0.005$					
0	16	0.82494	0.0046897			
0.5	13	0.82494	0.0035121			
1.0	12	0.82494	0.0021299			
1.5	12	0.82494	0.0021299			
1.99	12	0.82494	0.0021299			

Table 3. The Numerical Result of 8 DimensionTest Function with Gradient Descent

3.2. Numerical Results for Test Function with CGHGN

After comparing classical Armijo and its modification to the gradient descent algorithm, here is the next comparison on CGHGN. The test functions used remain the same as the test functions in the above sections. Similarly, for the value of the parameters used and the iteration termination criterion.

From Table 4 it is generally found that conjugate gradient does not work better than gradient descent in applying modified Armijo. This can be seen from the numerical results on Quadric, Himmenblau, and Zakharof functions. Even the performance is very bad on the Quadric function, with more iterations needed to achieve the same $||g_k||$ stopping criteria. Also, the $||g_k||$ obtained is worse than the classic Armijo.

Table 4.	The Numerical Results of The Two
	Variable Test Function with CGHGN

	Number of				
μ	iteration	Ε	$\ g_k\ $		
	(<i>k</i>)				
	Quadric	function with x_0 :	(1,2)		
0	8	9.435 (10 ⁻⁷)	0.0020482		
0.5	18	3.7116 (10 ⁻⁶)	0.0028629		
1.0	15	1.0485 (10 ⁻⁵)	0.0041436		
1.5	19	4.9341 (10 ⁻⁶)	0.003629		
1.99	13	7.0949 (10 ⁻⁶)	0.0033074		
	Zakharof	function with x_0 :	(1,2)		
0	4	7.3802 (10 ⁻⁸)	0.00081502		
0.5	6	5.1685 (10 ⁻⁹)	0.00021537		
1.0	6	5.1685 (10 ⁻⁹)	0.00021537		
1.5	6	5.1685 (10 ⁻⁹)	0.00021537		
1.99	6	5.1685 (10 ⁻⁹)	0.00021537		
	De Jong	function with x_0 :	(1,2)		
0	4	1.0207 (10 ⁻⁶)	0.0020206		
0.5	2	1.7711 (10 ⁻²⁸)	2.6617 (10 ⁻¹⁴)		
1.0	2	6.7025 (10 ⁻²⁸)	5.1778 (10 ⁻¹⁴)		
1.5	2	6.7025 (10 ⁻²⁸)	5.1778 (10 ⁻¹⁴)		
1.99	2	1.6852 (10 ⁻²⁷)	8.2102 (10 ⁻¹⁴)		
	Himmenbl	lau function with x	0 (0,0)		
0	12	8.8547 (10 ⁻⁸)	0.0039747		
0.5	13	$4.732(10^{-8})$	0.0018234		
1.0	23	4.1353 (10 ⁻⁷)	0.0046038		
1.5	15	3.2192 (10 ⁻⁸)	0.0033049		
1.99	12	2.4744 (10 ⁻⁷)	0.0033668		
McCormic function with x_0 (0,0)					
0	6	1.9132	0.0038449		
0.5	7	1.9132	0.0045575		
1.0	8	1.9132	0.0026397		
1.5	7	1.9132	0.0016163		
1.99	10	1.9132	0.0041537		

The CGHGN iteration behavior using both classical Armijo and its modification is not so different. It can be seen in Figure 4.a-d below. With various parameter values μ , the resulting iteration points are not much different in Himmenblau function.



Figure 4.a CGHGN with Classic Armijo ($\mu = 0$) on Himmenblau Function



Figure 4.b CGHGN with Modified Armijo ($\mu = 0.5$) in Himmenblau Function



Figure 4.c CGHGN with Modified Armijo ($\mu = 1$) in Himmenblau Function



Figure 4.d CGHGN with Modified Armijo ($\mu = 1.5$) in Himmenblau Function

Table 5 below shows CGHGN numerical results with modified Armijo on four-dimensional functions. The result is that CGHGN works very badly in applying modified Armijo.

Tabel 5. Numerical Result 4-dimensional	Test
Function with CGHGN	

	Number of	F	~		
μ iteration (k) L		Ľ	$ g_k $		
4-dimensional Powell Singular function with x_0					
		(1,1,1,1)			
0	74	2.5467 (10 ⁻⁵)	0.0033689		
0.5	1000	0.00053896	0.016547		
1.0	1000	0.00052487	0.016728		
1.5	1000	0.00052992	0.015748		
1.99	1000	0.00053591	0.016243		
4-0	limensional Wa	tson function with	x_0 (0,0,0,0)		
0	34	0.0060263	0.003837		
0.5	462	0.0060228	0.0041832		
1.0	528	0.0060492	0.004726		
1.5	449	0.0060409	0.003878		
1.99	559	0.0060495	0.0048206		
4-0	limensional Pen	alty function with	$x_0(1,2,3,4)$		
0	84	0.0062071	0.004998		
0.5	2	0.0017474	0.001944		
1.0	2	0.0017474	0.001944		
1.5	2	0.0017474 0.001944			
1.99	2	0.0017474	0.001944		
4-dim	4-dimensional Variably-Dimensioned with x_0 (0,0,0,0)				
0	12	8.7638 (10 ⁻⁷)	0.0018735		
0.5	85	$2.3254(10^{-6})$	0.0041347		
1.0	77	3.2597 (10-6)	0.0047175		
1.5	46	5.3615 (10-6)	0.0047064		
1.99	76	4.195 (10 ⁻⁶)	0.0048226		
4	-dimensional T	rigonometric funti	on with x_0		
	(0.25	5,0.25,0.25,0.25)	Ū		
0	12	0.00040346	0.0049897		
0.5	23	0.00034834	0.0034499		
1.0	20	0.00037274	0.0044723		
1.5	23	0.00034909	0.0038791		
1.99	20	0.00037369	0.0049191		
4-dimensional Penalty II function with x_0 (1.1.1.1)					
0	11	0.82484	0.00081602		
0.5	18	0.82484	0.00092696		
1.0	18	0.82485	0.0042525		
1.5	20	0.82485	0.0033585		
1.99	21	0.82485	0.003335		

In Table 5, it can be seen that the conjugate gradient only works well on the Penalty function. While in other functions, to meet the same termination criteria $(\varepsilon < 0.005),$ conjugate gradient with modified Armijo requires much more iteration. This is enough to show the ineffectiveness of Armijo modification if applied to this algorithm. In contrast, in Table 1 and Table 2, CGHGN with Classical Armijo works better than if classical Armijo is applied to the gradient descent. However, as discussed in this paper is how effective modified Armijo is applied to the

gradient descent and CGHGN, it is sufficient to answer that modified Armijo works more effectively on the gradient descent.

3.3. Comparison of Computational Time Gradient Descent and CGHGN

In addition to comparing numerical solutions of each algorithm by applying classical Armijo and its modifications, it can be compared computation time, ie the time required by the algorithm to solve the problem of minimizing the test functions until the desired stopping criterion is reached. Before reading the tables below, by comparison of the number of iterations as described in the above sections, it is possible to guess the computational time behavior required for each algorithm. For gradient descent, the average number of iterations decreases, so too is the computation time.

Tabel 6. Computational Time of Gradient Descent and CGHGN on Two-dimensional Function

	Gradient Descent		CGHGN	
μ	E	t	Ε	t
Zakharof function				
0	7.381 (10 ⁻⁸)	0.016	7.3802 (10 ⁻⁸)	0.016
0.5	$5.181(10^{-9})$	0.016	5.1685 (10 ⁻⁹)	0.015
1.0	$5.181(10^{-9})$	0.016	5.1685 (10 ⁻⁹)	0.016
1.5	$5.181(10^{-9})$	0.016	5.1685 (10 ⁻⁹)	0.015
1.99	$5.181(10^{-9})$	0	5.1685 (10 ⁻⁹)	0.016
	De	Jong fun	ction	
0	1.0207 (10-6)	0	1.0207 (10-6)	0.015
0.5	9.9104 (10 ⁻²⁹)	0.016	1.7711 (10 ⁻²⁸)	0.016
1.0	2.4155 (10 ⁻²⁸)	0	$6.7025(10^{-28})$	0.016
1.5	2.4155 (10 ⁻²⁸)	0	$6.7025(10^{-28})$	0.015
1.99	2.4755 (10 ⁻²⁸)	0	$1.6852(10^{-27})$	0.016
	Himm	enblau fi	unction	
0	1.9501 (10 ⁻⁷)	0.031	8.8547 (10 ⁻⁸)	0.031
0.5	$2.0832(10^{-8})$	0.015	4.732 (10 ⁻⁸)	0.016
1.0	1.6794 (10 ⁻⁷)	0.015	4.1353 (10 ⁻⁷)	0.016
1.5	3.8923 (10 ⁻⁸)	0.016	3.2192 (10 ⁻⁸)	0.016
1.99	$2.5695(10^{-7})$	0.016	2.4744 (10 ⁻⁷)	0
	McC	ormic fu	nction	
0	1.9132	0.875	1.9132	0.016
0.5	1.9132	0.406	1.9132	0.015
1.0	1.9132	0.016	1.9132	0.016
1.5	1.9132	0.015	1.9132	0.016
1.99	1.9132	0.015	1.9132	0.016

In Table 6 have not been able to prove the guess because the computation time difference is not so large on each parameter value μ , both on the gradient descent and on CGHGN. However, in Table 7, and Table 8 with larger dimensioned functions, it can prove that guess because the

computation time difference is large enough for each parameter change, especially from the value of $\mu = 0$ to other μ values. The considerable computation time difference can be seen, among others, on 4-dimension Powell Singular function and 4-dimension and 8-dimension Watson function. Gradient descent shows better results than CGHGN in terms of computational time in applying modified Armijo on average test function used, either 2, 4, or, 8-dimension.

Tabel 7. Computational Time of Gradient Descent and CGHGN on Four-dimensional Function

	Gradient Descent		CGHGN		
μ	Е	t	Ε	t	
4 dimension Powell Singular function					
0	0.00040193	2.156	2.5467 (10 ⁻⁵)	0.078	
0.5	0.00020607	0.125	0.00053896	1.031	
1.0	0.00020451	0.094	0.00052487	1.015	
1.5	0.00020795	0.078	0.00052992	0.985	
1.99	0.00020783	0.062	0.00053591	0.985	
	4 dimens	ion Wats	on function		
0	0.0060494	10.11	0.0060263	0.578	
0.5	0.0060433	0.75	0.0060228	3.969	
1.0	0.0060441	0.578	0.0060492	4.391	
1.5	0.0060496	0.547	0.0060409	3.734	
1.99	0.0060247	0.438	0.0060495	4.219	
	4 dimens	ion Pena	lty function		
0	0.0062071	0.031	0.0062071	0.032	
0.5	0.0017474	0.016	0.0017474	0.016	
1.0	0.0017474	0.016	0.0017474	0.015	
1.5	0.0017474	0.015	0.0017474	0.015	
1.99	0.0017474	0.016	0.0017474	0.015	
2	4 dimension Var	iably-Diı	nensioned functi	on	
0	$2.6045(10^{-6})$	0.266	8.7638 (10 ⁻⁷)	0.062	
0.5	1.2441 (10 ⁻⁹)	0.016	$2.3254(10^{-6})$	0.078	
1.0	1.2441 (10 ⁻⁹)	0.016	3.2597 (10 ⁻⁶)	0.063	
1.5	1.2441 (10 ⁻⁹)	0.015	5.3615 (10 ⁻⁶)	0.047	
1.99	1.2441 (10 ⁻⁹)	0.015	$4.195(10^{-6})$	0.062	
	4 dimension	Trigono	metric function		
0	0.00035521	0.031	0.00040346	0.015	
0.5	0.00033347	0.015	0.00034834	0.031	
1.0	0.00040127	0.015	0.00037274	0.032	
1.5	0.00039599	0.015	0.00034909	0.031	
1.99	0.00038882	0.015	0.00037369	0.032	
4 dimension Penalty II function					
0	0.82485	0.125	0.82484	0.094	
0.5	0.82485	0.031	0.82484	0.032	
1.0	0.82485	0.016	0.82485	0.031	
1.5	0.82485	0.015	0.82485	0.047	
1.99	0.82485	0.015	0.82485	0.032	

	Gradient Descent		CGHGN	
μ	Ε	t	Ε	t
	Fung	si Watson	dimensi 8	
0	0.0056431	40.39	0.0039089	3.5
0.5	0.0060244	3.703	0.0056966	14.266
1.0	0.0060305	2.25	0.0056511	16.031
1.5	0.005936	2.25	0.0054967	15.954
1.99	0.0061168	2.047	0.0053083	17.266
Fungsi Penalty II dimensi 8				
0	0.82494	0.125	0.82494	0.078
0.5	0.82494	0.047	0.82494	0.046
1.0	0.82494	0.047	0.82494	0.062
1.5	0.82494	0.031	0.82494	0.063
1.99	0.82494	0.031	0.82494	0.078

Table 8. Computational Time of Gradient Descentand CGHGN on Eight-dimensionalFunction

Of the two comparable parameters, a number of iterations required to achieve a required stopping criterion and computational time required to solve numerical minimization problem, it has been shown that gradient descent is better and more effective than CGHGN in applying the modified Armijo rule.

4. CONCLUSIONS

From the discussion above, it can be concluded that modified Armijo works very well on the gradient descent, not only in terms of the number of iterations required to achieve a stopping criterion, but also of computation time on the test functions tested. The parameter value μ , affecting its numerical performance, ie with the increasing value of this parameter, then the required iteration also becomes less. Similarly, the effect on program computing time.

The Armijo modification works very poorly on the conjugate gradient so that increase of parameter value μ cannot be seen affecting the number of iterations required.

The two variable test functions have not been able to answer exactly the comparison of the effectiveness of the application of modified Armijo on gradient descent and conjugate gradient. The larger dimension test functions respond to the comparison of the effective application of modified Armijo to the gradient descent and conjugate gradient. The modified Armijo is more effectively applied to gradient descent than conjugate gradient hybrid Gilbert-Nocedal.

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