

## Coincidence and Fixed point of Nonexpansive type Mappings in 2-Metric Spaces

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ABSTRACT. The aim of this paper is to prove a coincidence point theorem for a class of self mappings satisfying nonexpansive type condition under various conditions and a fixed point theorem is also obtained. Our results extend and generalizes the corresponding result of Singh et al. [7].

### 1. INTRODUCTION AND PRELIMINARIES

The concept of 2-metric space was introduced by Gähler ([2, 3, 4]) whose abstract properties were suggested by the area function in Euclidean space. Employing various contractive conditions Iseki [5] set out the tradition of proving fixed point theorems in 2-metric spaces. Later on, Naidu and Prasad [6] contributed few fixed point theorems in 2-metric spaces introducing the concept of weak commutativity.

Recently, Singh et al. [7] proved a fixed point theorem in 2-metric space for nonexpansive type mappings. They obtained the following result:

THEOREM 1.1. *Let  $(X, d)$  be a 2-metric space and  $T : X \rightarrow X$  be a self mapping satisfying the following nonexpansive type condition:*

$$(1.1) \quad \begin{aligned} d(Tx, Ty, u) \leq & \\ & a \max\{d(x, y, u), d(x, Tx, u), d(y, Ty, u), \frac{1}{2}[d(x, Ty, u) + d(y, Tx, u)]\} \\ & + b \max\{d(x, Tx, u), d(y, Ty, u)\} + c[d(x, Ty, u) + d(y, Tx, u)] \end{aligned}$$

for all  $x, y, u \in X$ , where  $a, b, c$  are real numbers such that  $a + b + 2c = 1$  and  $a \geq 0$ ,  $b > 0$ ,  $c > 0$ . Then  $T$  has a unique fixed point and  $T$  is continuous at the fixed point.

In this paper, we introduce a new class of self mappings satisfying the following nonexpansive type condition:

$$(1.2) \quad \begin{aligned} d(Tx, Ty, u) \leq & a(x, y) \max\{d(fx, fy, u), d(fy, Ty, u)\} \\ & + b \max\{d(fx, Tx, u), d(fy, Ty, u), d(y, Tx, u)\} \\ & + c[d(fx, Ty, u) + d(fy, Tx, u)] \end{aligned}$$

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for all  $x, y, u \in X$ , where  $a, b, c$  are real numbers such that  $\sup\{a(x, y) + b(x, y) + 2c(x, y)\} = 1$  and  $a(x, y) \geq 0$ ,  $\beta = \inf b(x, y) > 0$ ,  $\gamma = \inf c(x, y) > 0$ . Our condition is an extension of that of Ćirić ([1])(see also [8]).

Also, we will show that our condition (1.2) includes the above condition (1.1) of S. L. Singh et al. [7].

Now we give some definitions which are used frequently to prove our main results.

Gähler defined 2-metric space as follows:

DEFINITION 1.1. A 2-metric on a set  $X$  with at least three points is a non-negative real-valued mapping  $d : X \times X \times X \rightarrow R$  satisfying the following properties:

- (1) To each pair of points  $a, b$  with  $a \neq b$  in  $X$  there is a point  $c \in X$  such that  $d(a, b, c) \neq 0$ .
- (2)  $d(a, b, c) = 0$ , if at least two of the points are equal,
- (3)  $d(a, b, c) = d(b, c, a) = d(a, c, b)$ ,
- (4)  $d(a, b, c) \leq d(a, b, u) + d(a, u, c) + d(u, b, c)$  for all  $a, b, c, u \in X$ .

The pair  $(X, d)$  is called a 2-metric space.

DEFINITION 1.2. The sequence  $\{x_n\}$  is convergent to  $x \in X$  and  $x$  is the limit of this sequence if  $\lim_{n \rightarrow \infty} d(x_n, x, u) = 0$  for each  $u \in X$ .

DEFINITION 1.3. A sequence  $\{x_n\}$  is called Cauchy sequence if

$$\lim_{n, m \rightarrow \infty} d(x_n, x_m, u) = 0$$

for all  $u \in X$ . A 2-metric space in which every Cauchy sequence is convergent is called complete.

DEFINITION 1.4. Let  $f$  and  $g$  be two self mappings of a 2-metric space  $(X, d)$ . Then  $f$  and  $g$  are said to be compatible if  $\lim_{n \rightarrow \infty} d(fg x_n, gf x_n, u) = 0$  for each  $u \in X$ , whenever  $\{x_n\}$  is a sequence such that

$$\lim_{n \rightarrow \infty} f x_n = \lim_{n \rightarrow \infty} g x_n = t \in X.$$

## 2. MAIN RESULTS

THEOREM 2.1. Let  $(X, d)$  be a 2-metric space. Let  $T, f$  be self mappings of  $X$  satisfying nonexpansive type condition (1.2) with  $\sup\{a(x, y) + b(x, y) + 2c(x, y)\} = 1$  and  $a(x, y) \geq 0$ ,  $\beta = \inf b(x, y) > 0$ ,  $\gamma = \inf c(x, y) > 0$ . Let  $T(X) \subseteq f(X)$  and either

- (a)  $X$  is complete and  $f$  is surjective, or,
- (b)  $X$  is complete,  $f$  is continuous and  $T, f$  are compatible, or
- (c)  $f(X)$  is complete, or
- (d)  $T(X)$  is complete.

Then  $f$  and  $T$  have a coincidence point in  $X$ . Further, the coincidence point is unique, that is,  $f_p = f_q$ , whenever  $f_p = T_p$  and  $f_q = T_q$ ;  $p, q \in X$ .

PROOF. Let  $x = x_0$  be an arbitrary point in  $X$ . Since  $T(X) \subseteq f(X)$ , choose  $x_1$  so that  $y_1 = f x_1 = T x_0$ . In general, choose  $x_{n+1}$  such that  $y_{n+1} = f x_{n+1} = T x_n$  for all  $n = 0, 1, 2, \dots$ .

On applying inequality (1.2) and taking  $a(x_n, x_{n+1}) = a$ ,  $b(x_n, x_{n+1}) = b$  and

$c(x_n, x_{n+1}) = c$ , we get

$$\begin{aligned} d(fx_{n+2}, fx_{n+1}, fx_n) &= d(Tx_{n+1}, Tx_n, fx_n) \\ &\leq a \max\{d(fx_{n+1}, fx_n, fx_n), d(fx_{n+1}, Tx_{n+1}, fx_n)\} \\ &\quad + b \max\{d(fx_n, Tx_n, fx_n), d(fx_{n+1}, Tx_{n+1}, fx_{n+1}) \\ &\quad \quad \quad , d(fx_{n+1}, Tx_n, fx_n)\} \\ &\quad + c[d(fx_n, Tx_{n+1}, fx_n) + d(fx_{n+1}, Tx_n, fx_n)] \\ &= (a + b)d(fx_{n+1}, Tx_{n+1}, fx_n) \\ &= (a + b)d(fx_{n+2}, fx_{n+1}, fx_n) \end{aligned}$$

This implies that

$$(1 - (a + b))d(fx_{n+2}, fx_{n+1}, fx_n) \leq 0$$

Since  $1 - (a + b) > 0$ , we get

$$(2.1) \quad d(fx_{n+2}, fx_{n+1}, fx_n) = 0$$

On applying inequality (1.2) again and using triangular inequality and (2.1), we get

$$\begin{aligned} d(Tx_n, Tx_{n+1}, u) &\leq a \max\{d(fx_n, fx_{n+1}, u), d(fx_{n+1}, Tx_{n+1}, u)\} \\ &\quad + b \max\{d(fx_n, Tx_n, u), d(fx_{n+1}, Tx_{n+1}, u) \\ &\quad \quad \quad , d(fx_{n+1}, Tx_n, u)\} \\ &\quad + c[d(fx_n, Tx_{n+1}, u) + d(fx_{n+1}, Tx_n, u)] \\ &\leq a \max\{d(fx_n, Tx_n, u), d(fx_{n+1}, Tx_{n+1}, u)\} \\ &\quad + b \max\{d(fx_n, Tx_n, u), d(fx_{n+1}, Tx_{n+1}, u)\} \\ &\quad + cd(fx_n, Tx_{n+1}, u) \\ &= a \max\{d(fx_n, Tx_n, u), d(fx_{n+1}, Tx_{n+1}, u)\} \\ &\quad + b \max\{d(fx_n, Tx_n, u), d(fx_{n+1}, Tx_{n+1}, u)\} \\ &\quad + c[d(fx_n, Tx_{n+1}, Tx_n) + d(fx_n, Tx_n, u) \\ &\quad \quad \quad + d(Tx_{n+1}, Tx_n, u)] \\ &= a \max\{d(fx_n, Tx_n, u), d(fx_{n+1}, Tx_{n+1}, u)\} \\ &\quad + b \max\{d(fx_n, Tx_n, u), d(fx_{n+1}, Tx_{n+1}, u)\} \\ (2.2) \quad &\quad + c[d(fx_n, Tx_n, u) + d(fx_{n+1}, Tx_{n+1}, u)] \end{aligned}$$

Suppose that, for some  $n$ ,  $d(fx_{n+1}, Tx_{n+1}, u) > d(fx_n, Tx_n, u)$ , then from (2.2), we have

$$\begin{aligned} d(fx_{n+1}, Tx_{n+1}, u) &= d(Tx_n, Tx_{n+1}, u) \\ &\leq ad(fx_{n+1}, Tx_{n+1}, u) + bd(fx_{n+1}, Tx_{n+1}, u) \\ &\quad + c[d(fx_{n+1}, Tx_{n+1}, u) + d(fx_{n+1}, Tx_{n+1}, u)] \\ &= (a + b + 2c)d(fx_{n+1}, Tx_{n+1}, u) \\ &\leq d(fx_{n+1}, Tx_{n+1}, u) \end{aligned}$$

a contradiction. Hence we must have,  $d(fx_{n+1}, Tx_{n+1}, u) \leq d(fx_n, Tx_n, u)$ , or equivalently,

$$(2.3) \quad d(Tx_n, Tx_{n+1}, u) \leq d(Tx_{n-1}, Tx_n, u)$$

On applying inequality (1.2) again and evaluating  $a$ ,  $b$ ,  $c$  at  $(x_{n-1}, x_n)$ , we have

$$\begin{aligned}
d(y_n, y_{n+1}, u) &= d(Tx_{n-1}, Tx_n, u) \\
&\leq a \max\{d(fx_{n-1}, fx_n, u), d(fx_n, Tx_n, u)\} \\
&\quad + b \max\{d(fx_{n-1}, Tx_{n-1}, u), d(fx_n, Tx_n, u), \\
&\quad \quad d(fx_n, Tx_{n-1}, u)\} \\
&\quad + c[d(fx_{n-1}, Tx_n, u) + d(fx_n, Tx_{n-1}, u)] \\
&= a \max\{d(Tx_{n-2}, Tx_{n-1}, u), d(Tx_{n-1}, Tx_n, u)\} \\
&\quad + b \max\{d(Tx_{n-2}, Tx_{n-1}, u), d(Tx_{n-1}, Tx_n, u)\} \\
&\quad + cd(Tx_{n-2}, Tx_n, u) \\
&= ad(Tx_{n-2}, Tx_{n-1}, u) + bd(Tx_{n-2}, Tx_{n-1}, u) \\
(2.4) \quad &\quad + cd(Tx_{n-2}, Tx_n, u)
\end{aligned}$$

On applying inequality (1.2) again and using (2.1), (2.3) and by triangular inequality, we get

$$\begin{aligned}
d(Tx_{n-2}, Tx_n, u) &\leq \bar{a} \max\{d(fx_{n-2}, fx_n, u), d(fx_n, Tx_n, u)\} \\
&\quad + \bar{b} \max\{d(fx_{n-2}, Tx_{n-2}, u), d(fx_n, Tx_n, u), \\
&\quad \quad d(fx_n, Tx_{n-2}, u)\} \\
&\quad + \bar{c}[d(fx_{n-2}, Tx_n, u) + d(fx_n, Tx_{n-2}, u)] \\
&= \bar{a} \max\{d(Tx_{n-3}, Tx_{n-1}, u), d(Tx_{n-1}, Tx_n, u)\} \\
&\quad + \bar{b} \max\{d(Tx_{n-3}, Tx_{n-2}, u), d(Tx_{n-1}, Tx_n, u), \\
&\quad \quad d(Tx_{n-1}, Tx_{n-2}, u)\} \\
&\quad + \bar{c}[d(Tx_{n-3}, Tx_n, u) + d(Tx_{n-1}, Tx_{n-2}, u)] \\
&\leq \bar{a} \max\{d(Tx_{n-3}, Tx_{n-2}, Tx_{n-1}) + d(Tx_{n-3}, Tx_{n-2}, u) \\
&\quad + d(Tx_{n-2}, Tx_{n-1}, u), d(Tx_{n-1}, Tx_n, u)\} \\
&\quad + \bar{b} \max\{d(Tx_{n-3}, Tx_{n-2}, u), d(Tx_{n-1}, Tx_n, u), \\
&\quad \quad d(Tx_{n-1}, Tx_{n-2}, u)\} \\
&\quad + \bar{c}[d(Tx_{n-3}, Tx_{n-2}, Tx_n) + d(Tx_{n-3}, Tx_{n-2}, u) \\
&\quad \quad + d(Tx_{n-2}, Tx_n, u) + d(Tx_{n-1}, Tx_{n-2}, u)] \\
&\leq \bar{a} \max\{d(Tx_{n-3}, Tx_{n-2}, Tx_{n-1}) + d(Tx_{n-3}, Tx_{n-2}, u) \\
&\quad + d(Tx_{n-2}, Tx_{n-1}, u), d(Tx_{n-1}, Tx_n, u)\} \\
&\quad + \bar{b} \max\{d(Tx_{n-3}, Tx_{n-2}, u), d(Tx_{n-1}, Tx_n, u), \\
&\quad \quad d(Tx_{n-1}, Tx_{n-2}, u)\} \\
&\quad + \bar{c}[d(Tx_{n-3}, Tx_{n-2}, Tx_{n-1}) + d(Tx_{n-3}, Tx_{n-1}, Tx_n) \\
&\quad \quad + d(Tx_{n-2}, Tx_{n-1}, Tx_n) + d(Tx_{n-3}, Tx_{n-2}, u) \\
&\quad \quad + d(Tx_{n-2}, Tx_{n-1}, Tx_n) + d(Tx_n, Tx_{n-1}, u) \\
&\quad \quad + d(Tx_{n-2}, Tx_{n-1}, u) + d(Tx_{n-1}, Tx_{n-2}, u)]
\end{aligned}$$

$$\begin{aligned}
 &= \bar{a} \max\{d(Tx_{n-3}, Tx_{n-2}, u) + d(Tx_{n-2}, Tx_{n-1}, u) \\
 &\quad , d(Tx_{n-1}, Tx_n, u)\} \\
 &+ \bar{b} \max\{d(Tx_{n-3}, Tx_{n-2}, u), d(Tx_{n-1}, Tx_n, u) \\
 &\quad , d(Tx_{n-1}, Tx_{n-2}, u)\} \\
 &+ \bar{c}[d(Tx_{n-3}, Tx_{n-1}, Tx_n) + d(Tx_{n-3}, Tx_{n-2}, u) \\
 &\quad + d(Tx_n, Tx_{n-1}, u) + d(Tx_{n-2}, Tx_{n-1}, u) \\
 &\quad + d(Tx_{n-1}, Tx_{n-2}, u)] \\
 &\leq \bar{a} \max\{2d(Tx_{n-3}, Tx_{n-2}, u), d(Tx_{n-3}, Tx_{n-2}, u)\} \\
 &\quad + \bar{b} \max\{d(Tx_{n-3}, Tx_{n-2}, u), d(Tx_{n-3}, Tx_{n-2}, u) \\
 &\quad , d(Tx_{n-3}, Tx_{n-2}, u)\} \\
 &\quad + \bar{c}[d(Tx_{n-3}, Tx_{n-2}, u) + d(Tx_{n-3}, Tx_{n-2}, u) \\
 &\quad d(Tx_{n-3}, Tx_{n-2}, u) + d(Tx_{n-3}, Tx_{n-2}, u) \\
 &\quad + d(Tx_{n-3}, Tx_{n-1}, Tx_n)] \\
 &= [2(\bar{a} + \bar{b} + \bar{c}) - \bar{b}]d(Tx_{n-3}, Tx_{n-2}, u) \\
 (2.5) \quad &\leq (2 - \bar{b})d(Tx_{n-3}, Tx_{n-2}, u)
 \end{aligned}$$

where  $\bar{a}$ ,  $\bar{b}$ ,  $\bar{c}$  are evaluated at  $(x_{n-2}, x_n)$ .

At the bottom line of the above inequality,  $d(Tx_{n-3}, Tx_{n-1}, Tx_n) = 0$ . Because, let  $d(Tx_{n-3}, Tx_{n-1}, Tx_n) \neq 0$ , then applying (2.2), we get

$$\begin{aligned}
 d(Tx_{n-3}, Tx_{n-1}, Tx_n) &= d(Tx_{n-1}, Tx_n, Tx_{n-3}) \\
 &\leq a \max\{d(fx_{n-1}, Tx_{n-1}, Tx_{n-3}), d(fx_n, Tx_n, Tx_{n-3})\} \\
 &\quad + b \max\{d(fx_{n-1}, Tx_{n-1}, Tx_{n-3}), d(fx_n, Tx_n, Tx_{n-3})\} \\
 &\quad + c[d(fx_{n-1}, Tx_{n-1}, Tx_{n-3}) + d(fx_n, Tx_n, Tx_{n-3})] \\
 &\leq a \max\{d(Tx_{n-2}, Tx_{n-1}, Tx_{n-3}), d(Tx_{n-1}, Tx_n, Tx_{n-3})\} \\
 &\quad + b \max\{d(Tx_{n-2}, Tx_{n-1}, Tx_{n-3}), d(Tx_{n-1}, Tx_n, Tx_{n-3})\} \\
 &\quad + c[d(Tx_{n-2}, Tx_{n-1}, Tx_{n-3}) + d(Tx_{n-1}, Tx_n, Tx_{n-3})] \\
 &= (a + b + c)d(Tx_{n-1}, Tx_n, Tx_{n-3}) \\
 &< d(Tx_{n-1}, Tx_n, Tx_{n-3})
 \end{aligned}$$

a contradiction. Thus,  $d(Tx_{n-3}, Tx_{n-1}, Tx_n) = 0$ .

On using (2.3), (2.4), and (2.5), we get

$$\begin{aligned}
 d(Tx_{n-1}, Tx_n, u) &= d(y_n, y_{n+1}, u) \\
 &\leq ad(Tx_{n-2}, Tx_{n-1}, u) + bd(Tx_{n-2}, Tx_{n-1}, u) \\
 &\quad + c[(2 - \bar{b})d(Tx_{n-3}, Tx_{n-2}, u)] \\
 &\leq ad(Tx_{n-3}, Tx_{n-2}, u) + bd(Tx_{n-3}, Tx_{n-2}, u) \\
 &\quad + c(2 - \bar{b})d(Tx_{n-3}, Tx_{n-2}, u) \\
 &= (a + b + 2c)d(Tx_{n-3}, Tx_{n-2}, u) - \bar{b}cd(Tx_{n-3}, Tx_{n-2}, u) \\
 &\leq (1 - \bar{b}c)d(Tx_{n-3}, Tx_{n-2}, u) \\
 &\leq (1 - \beta\gamma)d(Tx_{n-3}, Tx_{n-2}, u) \\
 (2.6) \quad &\leq (1 - \beta\gamma)^{\frac{\alpha}{2}}d(y_0, y_1, u)
 \end{aligned}$$

Hence  $\{y_n\}$  is a Cauchy sequence.

For case (a) and (b), suppose that  $X$  is complete. Then Cauchy sequence  $\{y_n\}$  will converge to a point  $p$  in  $X$ .

**Case (a):** Since  $f$  is surjective, then there exist a point  $z$  in  $X$  such that  $p = fz$ . Now applying inequality (1.2), we get

$$\begin{aligned}
d(fz, Tz, u) &\leq d(fz, y_{n+1}, u) + d(fz, Tz, y_{n+1}) + d(Tz, y_{n+1}, u) \\
&\leq d(fz, y_{n+1}, u) + d(fz, Tz, y_{n+1}) + d(Tx_n, Tz, u) \\
&\leq d(fz, y_{n+1}, u) + d(fz, Tz, y_{n+1}) \\
&\quad + a(x, y) \max\{d(fx_n, fz, u), d(fz, Tz, u)\} \\
&\quad + b(x, y) \max\{d(fx_n, Tx_n, u), d(fz, Tz, u), d(fz, Tx_n, u)\} \\
&\quad + c(x, y)[d(fx_n, Tz, u) + d(fz, Tx_n, u)] \\
&\leq \sup_{x, y \in X} [a(x, y) + c(x, y)] \max [\max\{d(fx_n, fz, u), d(fz, Tz, u)\} \\
&\quad , d(fz, fx_{n+1}, u)] + \sup_{x, y \in X} [b(x, y) + c(x, y)] \max [\max\{d(fx_n, fx_{n+1}, u) \\
&\quad , d(fz, Tz, u), d(fz, fx_{n+1}, u)\}, d(fx_n, Tz, u) + d(fz, fx_{n+1}, u)] \\
&\quad + d(fz, y_{n+1}, u) + d(fz, Tz, y_{n+1})
\end{aligned}$$

Taking the limit as  $n \rightarrow \infty$ , we have

$$d(fz, Tz, u) \leq \sup_{x, y \in X} (b + c)d(fz, Tz, u) < d(fz, Tz, u)$$

implies that  $fz = Tz$ .

**Case (b):** Since  $f$  is continuous and  $f$  and  $T$  are compatible, we have

$$\lim_{n \rightarrow \infty} fy_n = fp \quad \text{and} \quad \lim_{n \rightarrow \infty} fx_n = \lim_{n \rightarrow \infty} Tx_n = \lim_{n \rightarrow \infty} y_{n+1} = p$$

and hence

$$(2.7) \quad \lim_{n \rightarrow \infty} d(fTx_n, Tfx_n, u) = 0$$

Using (2.5), we get

$$\begin{aligned}
d(fp, Tp, u) &\leq d(fp, fy_{n+1}, Tp) + d(fp, fy_{n+1}, u) + d(fy_{n+1}, u, Tp) \\
&\leq d(fp, fy_{n+1}, Tp) + d(fp, fy_{n+1}, u) + d(Tp, Tfx_n, u) \\
&\leq d(fp, fy_{n+1}, Tp) + d(fp, fy_{n+1}, u) \\
&\quad + a \max\{d(ffx_n, fp, u), d(fp, Tp, u)\} \\
&\quad + b \max\{d(ffx_n, Tfx_n, u), d(fp, Tp, u), d((fp, Tfx_n, u))\} \\
&\quad + c[d(ffx_n, Tp, u) + d(fp, Tfx_n, u)] \\
&\leq d(fp, fy_{n+1}, Tp) + d(fp, fy_{n+1}, u) \\
&\quad + \sup_{x, y \in X} [a(x, y) + b(x, y) + c(x, y)] \max \left\{ \max\{d(ffx_n, fp, u), \right. \\
&\quad d(fp, Tp, u)\}, \max\{d(ffx_n, Tfx_n, u), d(fp, Tp, u), \\
(2.8) \quad &\quad \left. d((fp, Tfx_n, u))\}, c[d(ffx_n, Tp, u) + d(fp, Tfx_n, u)] \right\}
\end{aligned}$$

Now we have

$$d(ffx_n, Tfx_n, u) \leq d(ffx_n, fTx_n, u) + d(fTx_n, Tfx_n, u) + d(ffx_n, Tfx_n, Tfx_n)$$

Using the continuity of  $f$  and the compatibility of  $f$  and  $T$ , it follows that

$$(2.9) \quad \lim_{n \rightarrow \infty} d(ffx_n, Tfx_n, u) = 0, \quad \lim_{n \rightarrow \infty} d(ffx_n, fTx_n, u) = 0$$

$$\lim_{n \rightarrow \infty} ffx_n = fp, \text{ implies that, } \lim_{n \rightarrow \infty} Tfx_n = fp$$

Taking limit as  $n \rightarrow \infty$  and using the inequality (2.7) and (2.8), we get

$$d(fp, Tp, u) \leq \sup_{x, y \in X} [a(x, y) + b(x, y) + c(x, y)]d(fp, Tp, u), \text{ , implies that, , } fp = Tp$$

**Case (c):**In this case,  $p \in f(X)$ . Let  $z \in f^{-1}p$ , then  $p = fz$ , and the proof is completed by Case (a).

To establish uniqueness, suppose that  $q$  is another coincidence point of  $f$  and  $T$ . Then from (1.2) with  $a, b, c$  evaluated at  $(p, q)$ , we have

$$\begin{aligned} d(Tp, Tq, u) &\leq a \max\{d(fp, fq, u), d(fq, Tq, u)\} \\ &\quad + b \max\{d(fp, Tp, u), d(fq, Tq, u), d(fq, Tp, u)\} \\ &\quad + c[d(fp, Tq, u) + d(fq, Tp, u)] \\ &\leq (a + b + 2c)d(Tp, Tq, u) \end{aligned}$$

Hence  $Tp = Tq$ .

**COROLLARY 2.1.** *Let  $(X, d)$  be a complete 2-metric space and  $T$  be a self map of  $X$  satisfying (1.2) with  $f = I$ , the identity mapping on  $X$ . Then  $T$  has a unique fixed point and at this fixed point  $T$  is continuous.*

**PROOF.** The existence and uniqueness of the fixed point comes from Theorem (2.1) by setting  $f = I$ .

To prove continuity at the unique fixed point  $p$ , we apply inequality (1.2), where  $a, b, c$  are evaluated at  $(y_n, p)$ .

$$\begin{aligned} d(Ty_n, p, u) &= d(Ty_n, Tp, u) \\ &\leq a \max\{d(y_n, p, u), d(p, Tp, u)\} \\ &\quad + b \max\{d(y_n, Ty_n, u), d(p, Tp, u), d(p, Ty_n, u)\} \\ &\quad + c[d(y_n, Tp, u) + d(p, Ty_n, u)] \end{aligned}$$

Taking limit as  $n \rightarrow \infty$  yields

$$\lim_{n \rightarrow \infty} d(Ty_n, p, u) \leq (b + c) \lim_{n \rightarrow \infty} d(p, Ty_n, u) < \lim_{n \rightarrow \infty} d(p, Ty_n, u)$$

a contradiction. Therefore,  $\lim_{n \rightarrow \infty} Ty_n = p = Tp$ . □

**REMARK 2.1.** Our condition (1.2) includes condition (1.1) of [7] if we define, with  $f = I$  the identity mapping,

$$m(x, y, u) = \max\{d(x, y, u), d(x, Tx, u), d(y, Ty, u), \frac{1}{2}[d(x, Ty, u) + d(y, Tx, u)]\}.$$

For each  $x, y \in X$  such that

$$m(x, y, u) = \max\{d(x, Tx, u), d(y, Ty, u)\}$$

define  $a(x, y) = 0, b(x, y) = a + b, c(x, y) = c$ .

For each  $x, y \in X$  such that

$$m(x, y, u) = \frac{1}{2}[d(x, Ty, u) + d(y, Tx, u)]$$

define  $a(x, y) = 0, b(x, y) = b, c(x, y) = a + 2c$ . Hence our Theorem (2.1) is a proper generalization of [7]. □

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